126-TRC-19-006

SAFETY COMPLIANCE TESTING FOR FMVSS 126 Electronic Stability Control Systems

FCA US LLC 2019 RAM 1500 NHTSA No. C20190303

TRANSPORTATION RESEARCH CENTER INC. 10820 State Route 347 East Liberty, Ohio 43319



August 16, 2019

FINAL REPORT

Prepared Under Contract No.: DTNH22-16-D-00027

U. S. DEPARTMENT OF TRANSPORTATION
National Highway Traffic Safety Administration
Enforcement
Office of Vehicle Safety Compliance
1200 New Jersey Avenue, SE
West Building, 4th Floor (NEF-210)
Washington, DC 20590

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| Prepared By: | David Karle |
|----------------|---------------------------|
| | David Karls |
| Approved By: | Jordanfining |
| Approval Date: | Jordan Piening 7-30-19 |
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| | | 1200 New Jersey Aver Washington, D.C. 2059 | | |
| | | Email: tis@nhtsa.dot.g | | |
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1.0 PURPOSE OF COMPLIANCE TEST

The purpose of this test is to determine if the test vehicle, a MY 2019 RAM 1500, appears to meet the minimum equipment and performance requirements stated in Federal Motor Vehicle Safety Standard (FMVSS) 126, "Electronic Stability Control Systems."

This standard establishes performance and equipment requirements for Electronic Stability Control (ESC) Systems installed in passenger cars, multipurpose passenger vehicles, trucks, and buses with a gross vehicle weight rating of 4,536 kilograms or less.

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS

Testing of the MY 2019 RAM 1500 was conducted at Transportation Research Center (TRC) in accordance with NHTSA TP-126-03, dated September 9, 2011.

The vehicle was inspected to ensure it was equipped with an ESC System that:

- Augments vehicle directional stability by applying and adjusting brake torques individually at each wheel to induce a correcting yaw moment to a vehicle;
- Is computer controlled with the computer using a closed-loop algorithm to limit vehicle oversteer and to limit vehicle understeer;
- Has a means to determine the vehicle's yaw rate and to estimate its side slip or side slip derivative with respect to time;
- Has a means to monitor driver steering inputs;
- Has an algorithm to determine the need, and a means to modify engine torque, as necessary, to assist the driver in maintaining control of the vehicle, and
- Is operational over the full speed range of the vehicle (except at vehicle speeds less than 20km/h (12.4mph), when being driven in reverse, or during system initialization).

The vehicle was subjected to a 0.7Hz Sine with Dwell (SWD) Steering Maneuver to ensure that it would meet the stability and responsiveness requirements of the standard as follows:

- At 1.00 second after completion of steer (COS) of a required sine with dwell steering input, the yaw rate of the vehicle must not exceed 35 percent of the first peak value of yaw rate recorded after the steering wheel angle changes sign (between first and second peaks during the same test run).
- At 1.75 seconds after completion of steer (COS) of a required sine with dwell steering input, the yaw rate of the vehicle must not exceed 20 percent of the first peak value of yaw rate recorded after the steering wheel angle changes sign (between first and second peaks during the same test run).

The lateral displacement of the vehicle center of gravity with respect to its initial straight path must be at least 1.83 m (6 feet) for vehicles with a GVWR of 3,500kg (7,716 lb) or less, and 1.52 m (5 feet) for vehicles with GVWR greater than 3,500kg (7,716 lb) when computed 1.07 seconds after the Beginning of Steer (BOS) at the specified steering wheel angles.

System malfunction simulations were executed to verify vehicle could identify and indicate a malfunction.

System related malfunction and Off telltales, and related controls were inspected for required identification and labeling.

Any deviation(s) from the conditions (i.e. environmental, loading, etc.) stated in NHTSA test procedure (TP-126-03) are noted in the remarks section of the applicable data sheets. Testing with any deviation(s) from the specified conditions was performed at the request of the customer, having decided that the deviation(s) were not likely to have a significant positive or negative impact on vehicle performance.

The vehicle's ESC System appears to meet the performance and equipment requirements as required by FMVSS 126. The test results are summarized on the following summary sheet.

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS ... continued

DATA SUMMARY (Sheet 1 of 2)

| VEHICLE MAKE/MODEL/BODY STYLE: RAM / 1500 / Truck | |
|--|-------------|
| VEHICLE NHTSA NO.: C20190303 VIN: 1C6SRFGT1KN | l552167 |
| VEHICLE TYPE: <u>Truck</u> DATE OF MANUFACTURE: <u>05</u> | 5-18 |
| LABORATORY: Transportation Research Center Inc. | |
| REQUIREMENTS | PASS/FAIL |
| ESC Equipment and Operational Characteristics (Data Sheet 2) | |
| The vehicle is to be equipped with an ESC System that meets the equipment and operational characteristics requirements. (S126, S5.1, S5.6) | <u>PASS</u> |
| ESC Malfunction Telltale – Location, Labeling and Bulb Check (Data Sheet 3) | |
| Telltale meets the requirements for mounting, symbol or text, color and check of lamp function (S126, S5.3.1, S5.3.2, S5.3.4, S5.3.5, S5.3.6 and S5.3.8) | PASS |
| "ESC Off" and other System Controls and Telltale (Data Sheet 3 & 4) | |
| If provided, telltale meets the requirements for mounting, symbol, or | PASS |
| text, color and check of lamp function (S126, S5.5.1, S5.5.2, S5.5.3, S5.5.6, S5.5.7, S5.5.8) | |
| If provided, off control meets the label requirements (S126, S5.4.3) | PASS |
| If provided, off control and other system controls as well as the ESC | PASS |
| off telltale meets the operational requirements (S126, S5.4, S5.4.1, S5.4.4, S5.5.4, and S5.5.9) | |

2.0 TEST PROCEDURE AND DISCUSSION OF RESULTS ... continued

DATA SUMMARY (Sheet 2 of 2)

| REQUIREMENTS | PASS/FAIL |
|--|-------------|
| Vehicle Lateral Stability (Data Sheet 8) | |
| Yaw Rate Ratio at 1.00 second after COS is less than 35% of peak value. (S126, S5.2.1) | PASS_ |
| Yaw Rate Ratio at 1.75 seconds after COS is less than 20% of peak value. (S126, S5.2.2) | <u>PASS</u> |
| Vehicle Responsiveness (Data Sheet 8) | |
| Lateral displacement at 1.07 seconds after BOS is at least 1.83 m (6 feet) for vehicles with a GVWR of 3,500 kg (7,716 lbs.) or less, and 1.52 m (5 feet) for vehicles with a GVWR greater than 3,500 kg (7,716 lbs.). (S126 S5.2.3) | PASS |
| ESC Malfunction Warning (Data Sheet 9) | |
| Warning is provided to driver after malfunction occurrence. (S126. S5.3) | <u>PASS</u> |
| Malfunction telltale stayed illuminated as long as malfunction existed and must extinguish after malfunction was corrected. (S126, S5.3.3 and S5.3.7) | PASS |

REMARKS:

3.0 TEST DATA

DATA SHEET 1 (Sheet 1 of 2) TEST VEHICLE INSPECTION AND TEST PREPARATION

| VEHICLE MAKE/MODEL/BODY STYLE: | RAM / 1500 / Truck |
|---|--|
| NHTSA No.: C20190303 | TEST DATE: 7-24-19 |
| VIN: 1C6SRFGT1KN552167 | MANUFACTURE DATE: 05-18 |
| GVWR: <u>3,221</u> KG FRONT GAWR: <u>1,770</u> | KG REAR GAWR <u>1,860</u> KG |
| SEATING POSITIONS: FRONT 3 | MID REAR3 |
| ODOMETER READING AT START OF TEST: | 35 (56) Miles (Kilometers) |
| DESIGNATED TIRE SIZE(S) FROM VEHICLE Front Axle 275/65R18 | LABELING: Rear Axle275/65R18 |
| 1 1011(71XIC | 1001 7 Mic |
| INSTALLED TIRE SIZE(S) ON VEHICLE: | |
| From Tire Sidewall Front Axle | Rear Axle |
| Manufacturer and Model Bridgestone Due | eler H/T_ Bridgestone Dueler H/T_ |
| Tire Size Designation 275/65R18 | 275/65R18 |
| TIN Left Front <u>DOT 9BYJ DHT 1518</u> | Right Front DOT 9BYJ DHT 1518 |
| Left Rear <u>DOT 9BYJ DHT 1518</u> | Right Rear DOT 9BYJ DHT 1518 |
| Are installed tire sizes same as labeled tire size If no, contact COTR for further guidance. | |
| DRIVE CONFIGURATIONS (MARK ALL THATE X Two Wheel Drive (2WD): () Front Wheel Drive (AWD) Four Wheel Drive Automatic – differentic X Four Wheel Drive High Gear Locked Control X Four Wheel Drive Low Gear (4WD Low Other (define) | eel Drive (X) Rear Wheel Drive al not locked full time (4WD Automatic) enter Differential (4WD HGLD) |
| CALLEL COENTRE |) |

DATA SHEET 1 (Sheet 2 of 2) TEST VEHICLE INSPECTION AND TEST PREPARATION

DRIVE CONFIGURATIONS AND MODES: (ex. default, performance, off-road)
(For each of the vehicle's drive configurations identify available operating modes)

| (I of each of the ver | iicie s urive | comigurations ident | ily available ope | rating modes) |
|--------------------------------|---------------|----------------------|-------------------|------------------------|
| Drive Configu | uration | 2WD - RWD | | <u>-</u> |
| Mode(s) | def | ault | | - |
| Drive Config | uration | 4WD High | | |
| Mode(s) | | 4WD High off-road | | - |
| Drive Config | uration | 4WD Low | | |
| Mode(s) | | off-road | | . |
| | | | | |
| VEHICLE STABILI | TY SYSTE | MS (Check applicat | ole technologies | s): |
| X_ESC | | | | Roll Stability Control |
| Active Suspe | ension | X Electronic Thrott | le Control X | _Active Steering |
| X_ABS | | | | |
| List other systems; | | | | |
| REMARKS: | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| RECORDED BY: _ APPROVED BY: | | | | 7-30-19 7-30-19 |

DATA SHEET 2 (Sheet 1 of 2) ESC SYSTEM HARDWARE AND OPERATIONAL CHARACTERISTICS

| VEHICLE MAKE/MODEL/BODY | STYLE: _ | RAM / 1500 / | Truck | _ |
|--|-------------------|---|---------------------|-----------------------------|
| NHTSA No.: C20190303 | | TEST DATE:_ | 7-24-19 | |
| ESC SYSTEM IDENTIFICATION | l: | | | |
| Manufacturer / Model | Continer | ital Teves MK100X | Т | |
| ESC SYSTEM HARDWARE (Che X Electronic Control Unit X Wheel Speed Sensors Yaw Rate Sensor | X Hyd | raulic Control Unit ering Angle Sensor | ensor | |
| List other components; | | | | |
| ESC SYSTEM OPERATIONAL (| CHARACT | TERISTICS: | | |
| System is capable of generating I | brake torc | ues at each wheel | X | _ Yes (PASS) _ No (FAIL) |
| Brief explanation with reference to | | | | _ |
| The hydraulic control unit with an | | | | |
| pressure sensor is able to adjust valves and activation of the pump | | | | |
| valves and activation of the pump | , macpen | dent from the drive | 1 3 branc aci | dation. |
| System is capable of determining | yaw rate | | X | _ Yes (PASS) _ No (FAIL) |
| Brief explanation with reference to | • | | | |
| The ESC system uses a yaw ra | <u>ite sensoi</u> | r for the determina | tion of the y | vaw rate of the |
| vehicle. | | | | |
| System is capable of monitoring of | driver stee | ering input | X | _ Yes (PASS) _ No (FAIL) |
| Brief explanation with reference to | • | | | |
| The actual value of driver steering | g input is | supplied by a steer | <u>ing angle se</u> | nsor. |
| | | | | |

DATA SHEET 2 (Sheet 2 of 2) ESC SYSTEM HARDWARE AND OPERATIONAL CHARACTERISTICS

ESC SYSTEM OPERATIONAL CHARACTERISTICS (continued):

| System is capable of estimating side slip or side | slip derivative | X Yes (PASS) No (FAIL) |
|--|--|----------------------------------|
| Brief explanation with reference to data collected The ESC uses the yaw rate sensor and lateral acousting of the vehicle yaw behavior and the estimation of | celeration sensor | r for the determination |
| System is capable of modifying engine torque du | ring ESC activation | on. X Yes (PASS) No (FAIL) |
| Brief explanation of method used to modify engin The ESC system can perform a reduction of engine request via the engine management interface. Fourth will use throttle, spark timing and fuel shut of | ne torque by sen or most if not all a | ding an engine torque |
| | | |
| System is capable of activation at speeds of 20 k and higher. | m/h (12.4 mph) | XYes (PASS) No (FAIL) |
| Speed system becomes active. ESC system becomes | comes fully active | at 13.8 km/h. |
| System is capable of activation during the following phases (acceleration, deceleration, coasting, and activation of ABS or traction control). | • | X Yes (PASS No (FAIL) |
| Vehicle manufacturer submitted documentation e ESC system mitigates understeer? | explaining how the | Yes (PASS No (FAIL) |
| DATA INDICATES COMPLIANCE | PASS/FAIL | PASS |
| RECORDED BY: David Karls | DAT | E: <u>7-30-19</u> |
| APPROVED BY: Jordan Piening | DAT | E: 7-30-19 |

DATA SHEET 3 (Sheet 1 of 4) ESC MALFUNCTION AND OFF TELLTALES Location, Labeling and Bulb Check

| VEHICLE MAKE/MODEL/BODY STYLE: RAM / 1500 / Truck |
|--|
| VEHICLE NHTSA NO. <u>C20190303</u> TEST DATE: <u>7-24-19</u> |
| |
| ESC Malfunction Telltale |
| Vehicle is equipped with malfunction telltale? X Yes (Pass)No (Fail) |
| Telltale Location Inside the tachometer |
| Telltale is mounted inside the occupant compartment in front of and in clear view of the driver? |
| X Yes (Pass) No (Fail) If no, explain |
| Malfunction Telltale symbol or abbreviation required by FMVSS No. 101. X Vehicle uses this symbol |
| Or ESCVehicle uses this symbolVehicle uses this abbreviationOther (Fail) |
| Note any words or additional symbols used. |
| |
| |
| Is ESC malfunction telltale part of a common space? Yes X No |
| Is ESC malfunction telltale also used to indicate activation of the ESC system? |
| XYesNo |
| If yes, explain telltale operation during ESC activation: |
| During ESC activation, the ESC telltale flashes. |

3.0 DATA SHEETS....continued

DATA SHEET 3 (Sheet 2 of 4) ESC MALFUNCTION AND OFF TELLTALES Location, Labeling and Bulb Check

"ESC OFF" Telltale (if provided)

| Vehicle is equipped with "ESC Off" telltale? | | | XYes | No |
|--|--------------------|----------------------------|--|-------|
| Is "ESC OFF" telltal telltale? | le combined with ' | 'ESC Malfunction" | telltale utilizing a t | • |
| Telltale Location | Inside the | tachometer | | |
| Telltale is mounted driver? | · | nt compartment in | | |
| "ESC OFF" Telltale Or OFF Note any words or a | ESC OFF | X Vehicle Vehicle Other (F | uses this symbol uses this abbrevia | ation |
| | | | | |
| Is ESC Off telltale r | part of a common | snace? | Yes X | No |

3.0 DATA SHEETS....continued

DATA SHEET 3 (Sheet 3 of 4) ESC MALFUNCTION AND OFF TELLTALES Location, Labeling and Bulb Check

| Function: Identify position of starting system | when telltale illuminates. |
|---|--|
| ☐ OFF/LOCK ⊠ON/RUN | ☐ Between OFF/LOCK and ON/RUN☐ Between ON/RUN and Start |
| Is telltale yellow in color? X | Yes No (fail) |
| Time telltale remains illumin | ated 3 seconds |
| Note: If telltale is part of cor check of lamp functio | mmon space, it is not required to illuminate during this |
| Starter Interlock: Does vehicle have any starter, tran the telltale lamp check functions? | smission or other interlocks that affect operation of YesX_ No |
| If yes, describe the interlock feature | э: |
| | on (If separate from Malfunction Telltale): when "ESC OFF" telltale illuminates. |
| ☐ OFF/LOCK 図 ON/RUN | ☐ Between OFF/LOCK and ON/RUN☐ Between ON/RUN and Start |
| Is telltale yellow in color? _ | X Yes No (fail) |
| Time telltale remains illumin | ated <u>3</u> seconds |
| Note: If telltale is part of cor during the check of la | mmon space, it is not required to illuminate imp function. |

3.0 DATA SHEETS....continued

DATA SHEET 3 (Sheet 4 of 4) ESC MALFUNCTION AND OFF TELLTALES Location, Labeling and Bulb Check

| Starter Interlock: Does vehicle have any starter, transmission or other interlocks that affect operation of the "ESC OFF" telltale lamp check functions? Yes X No | | | | |
|---|---------------------------------------|--|--|--|
| If yes, describe the interlock feature: | | | | |
| | | | | |
| DATA INDICATES COMPLIANCE | PASS/FAIL PASS | | | |
| REMARKS: | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| RECORDED BY: <u>David Karls</u> APPROVED BY: <u>Jordan Piening</u> | DATE: <u>7-30-19</u> DATE: 7-30-19 | | | |

DATA SHEET 4 (Sheet 1 of 4) ESC AND ANCILLARY SYSTEM CONTROLS

"ESC OFF" Controls Identification and Operational Check:

| Is the vehicle equipped wit system or place the ESC performance requirements | system in a | mode or mo | | |
|--|---------------------|------------------------------|--|-----------------|
| | | | <u>X</u> Ye | es No |
| Type of control or controls (mark all that apply) | provided? | Х | _Dedicated "ESC _Multi-functional o "ESC Off" mode _ Other (describe) | control with an |
| REMARKS: | | | | |
| *Electronic Stability Contro High. | l cannot be tu | rned off by tl | ne driver in 2WD n | node, only 4WD |
| Identify each control location | on, labeling an | d selectable | modes. | |
| First Control: (If applicable) | Labeling ModesTr | Skidding car action Contr | ole, under HVAC or symbol, with "Off ol off – momentary hold for 5 seconds | " underneath |
| "ESC OFF" Control identifi | cation symbol | or abbreviat | ion required by FN | //VSS No. 101. |
| OFF OF ESC | OFF | X | _Vehicle uses this _Vehicle uses this | • |
| Note any words or addition | al symbols us | ed. | | |
| | | | | |

DATA SHEET 4 (Sheet 2 of 4) ESC AND ANCILLARY SYSTEM CONTROLS

| Second Control: | | | | | |
|---|----------------------|-------------|-----------------|------------------------------|---|
| (If applicable) | Labeling | | | | |
| | Modes | | | | |
| "ESC OFF" Control identifi | cation symbol or a | bbreviation | required by F | MVSS No. 101. | |
| OFF Or ESC | COFF | | ehicle uses the | is symbol is abbreviation | |
| Note any words or additior | nal symbols used. | | | | |
| | | | | | |
| Identify standard or defaul | t drive configuratio | n <u>D</u> | efault - 2WD | | |
| | | | | | |
| Verify standard or default o | drive configuration | selected. | <u>X</u> Y | /es No | |
| Does the "ESC Off" telltale of the "ESC Off" mode on | | | the ESC off c | ontrol or selection | |
| | | NA | X Yes _ | No (fail) | |
| Does the "ESC Off" telltale ("Run") to "Lock" or "Off" a | | | | | |
| | _ | NA | X Yes _ | No (fail) | |
| If no, describe how the off | control functions: | | | | |
| | | | | | _ |

DATA SHEET 4 (Sheet 3 of 4) ESC AND ANCILLARY SYSTEM CONTROLS

If a multi-function control is provided, cycle through each mode setting on the control and record which modes illuminate the "ESC Off" telltale. Also, for those modes that illuminate the "ESC Off" telltale, identify if the telltale extinguishes upon cycling the ignition system.

| Control Modes | "ESC Off" telltale illuminates upon activation of control? (Yes/No) | "ESC Off" telltale extinguishes upon cycling ignition? (Yes/No) |
|-------------------------|--|--|
| Traction Control off | Yes | Yes |
| ESC off (4WD High only) | Yes | Yes |
| | | |

| | on" ("Run") to "Lock" or "Off" and then back again to the "On" |
|---------------------------|---|
| | NAX Yes No (fail) |
| Other System Controls t | hat have an ancillary effect on ESC Operation: |
| the ESC System or place | vith any ancillary controls that upon activation may deactivate e the ESC System in a mode or modes that may no longer equirements of the standard? |
| | XYesNo |
| List and describe each co | ntrol (i.e. alternate drive configuration selection controls): |
| Ancillary Control: | System 4WD Low Control Description Shift to N, hold button for 3 seconds Labeling "4WD Low" |
| Ancillary Control: | SystemN/A Control Description Labeling |

DATA SHEET 4 (Sheet 4 of 4) ESC AND ANCILLARY SYSTEM CONTROLS

Activate each control listed above and record whether the control illuminates the "ESC Off" telltale. Also, record warnings or messages provided regarding the ESC System.

| Ancillary Control | Control Activates "ESC Off" Telltale? (Yes/No) | Warnings or Messages Provided | | |
|---|--|-------------------------------|--|--|
| 4WD Low | Yes | | | |
| | | | | |
| | | | | |
| For those controls that illuminate the "ESC Off" telltale above identify if the "ESC Off" telltale extinguishes upon cycling the ignition system. | | | | |

| Ancillary Control | "ESC Off" telltale extinguishes upon cycling ignition? (Yes/No) |
|-------------------|---|
| 4WD Low | No |
| | |
| | |

For each control that illuminates the "ESC Off" telltale, did the telltale extinguish when the ignition is cycled from "On" ("Run") to "Lock" or "Off" and then back again to the "On" ("Run") position? If the control activated places the vehicle into a low-range four-wheel drive configuration designed for low-speed, off—road driving, the ESC System may remain turned off after the ignition has been cycled off and then back on and therefore the "ESC Off" telltale may not extinguish.

| the "ESC Off" telltale may not extinguish. — | NA | X | Yes | _ No (fail) |
|---|----|---|----------------------------|-------------|
| DATA INDICATES COMPLIANCE: | | | PASS/FAIL _ | PASS |
| REMARKS: | | | | |
| | | | | |
| | | | | |
| | | | | |
| RECORDED BY: <u>David Karls</u> APPROVED BY: Jordan Piening | | - | DATE: 7-30- DATE: 7-30- | |
| APPROVED BY: <u>Jordan Piening</u> | | | DATE. 1-30 | 13 |

DATA SHEET 5 (Sheet 1 of 3) VEHICLE AND TEST TRACK DATA

| VEHICLE MAKE/M | MODEL/BODY | STYLE: | RAM / 1500 | / Truck | _ |
|-----------------------|---|---|--------------------------------|---------------------|-------------------|
| NHTSA No.: | C20190303 | | TEST DATE | :7-24-1 | 19 |
| Test Track Requir | rements: | Test Surface | Slope (0-1 % | b) | 1_% |
| | | Peak Friction | n Coefficient (| at least 0.9) | 0.93 |
| Test Track Data Mo | • | | | Yes/No | Yes |
| Full Fluid Levels: | Fuel N/A | Coolant | X Other | Fluids Was | sher (specify) |
| Tire Pressures: | Required: | Front Axle | <u>250</u> kPa | Rear Axle | <u>250</u> kPa |
| | Actual: | LF <u>250</u> LR <u>250</u> | | RF 250 RR 250 | |
| Vehicle Dimensio | ns: Track | Width <u>173.5</u> | _cm Whee | elbase <u>367.4</u> | _cm |
| Vehicle weight rat | tings: GAW | R Front 1,77 | <u>0 </u> KG GAW | /R Rear <u>1,8</u> | <u>60</u> KG |
| | Unloa | aded Vehicle | Weight (UVV | V) | |
| Front Axle 141 | 1 <u>0.4</u> KG | Left Front | 717.8 KG | Right Fron | t <u>692.6</u> KG |
| Rear Axle 97 | <u>4.4 </u> KG | Left Rear | 499.0 KG | Right Rear | 475.4 KG |
| | Tot | al UVW | <u>2384.8</u> KG | | |
| Baseline W | eight and Ou | trigger Selec | tion (only for | MPVs, Trucks | s, Buses) |
| Calculated Baselin | e Weight (UVV | V+ 73 kg) | | 2457.8 K | G |
| Standard - E and u | uired ("Light," " eline weight un Baseline weigh under 2,722 kg seline weight e | der 1,588 kg t equal to or g (6,000 lbs.) | (3,500 lbs.) greater than 1 | | , |

DATA SHEET 5 (Sheet 2 of 3) VEHICLE AND TEST TRACK DATA

UVW with Outriggers (only for MPVs, Trucks, Buses)

Front Axle 1438.8 KG Left Front 730.0 KG Right Front 708.8 KG

Rear Axle 1006.2 KG Left Rear 517.2 KG Right Rear 489.0 KG

Total UVW w/ Outriggers 2445.0 KG

Loaded Vehicle Weight w/ Driver and Instrumentation (No Ballast)

 Front Axle
 1528.2
 KG
 Left Front
 782.2
 KG
 Right Front
 746.0
 KG

 Rear Axle
 1052.2
 KG
 Left Rear
 540.4
 KG
 Right Rear
 511.8
 KG

 Vehicle Weight
 2580.4
 KG

Ballast Required = [Total UVW + 168 KG] - Loaded Weight w/ Driver and Instrumentation

= [2445.0 KG + 168 KG] - 2580.4 KG

= ____ 32.6 KG

Total Loaded Vehicle Weight w/Driver, Instrumentation and Ballast

Front Axle 1546.2 KG Left Front 791.8 KG Right Front 754.4 KG

Rear Axle 1066.6 KG Left Rear 547.4 KG Right Rear 519.2 KG

Total Loaded Vehicle Weight 2612.8 KG

DATA SHEET 5 (Sheet 3 of 3) VEHICLE AND TEST TRACK DATA

| Center of Gravity and Inertial Sensing System Location at Loaded Vehicle Condition | | | | |
|--|--|--------------------------------|--|--|
| x-distance (longitudinal) | Point of reference is the front axle centerline. (Positive from front axle toward rear of vehicle.) | | | |
| y-distance (lateral) | Point of reference is the vehicle of (Positive from the center toward to | | | |
| z-distance (vertical) | Point of reference is the ground p (Positive from the ground up.) | lane. | | |
| Locations: | | | | |
| | Center of Gravity | Inertial Sensing System | | |
| x-distance | <u>150.0</u> _cm | <u>190.6</u> _cm | | |
| y-distance | <u>-2.2</u> cm | <u>-2.8</u> cm | | |
| z-distance | <u>72.4</u> _cm | 107.9cm | | |
| Roof Height: | <u>190.6</u> _cm | | | |
| Distance Bet | ween Body Roll Sensors: | <u>213.2</u> cm | | |
| is estimated to be 38% of | re (TP-126-03) states that the vehof the vehicle's roof height. The ed using the individual corner weight. | lateral and longitudinal CG | | |
| REMARKS: | | | | |
| | | | | |
| RECORDED BY: <u>David</u> APPROVED BY: <u>Jorda</u> | Karls n Piening | DATE: 7-30-19 DATE: 7-30-19 | | |

DATA SHEET 6 (Sheet 1 of 3) BRAKE AND TIRE CONDITIONING

| VEHICLE MAKE/MODEL/BODY | STYLE: <u>RAM / 1500</u> | / Iruck |
|---|------------------------------|--------------------------|
| VEHICLE NHTSA No.: C20 | 0190303 | |
| Measured Cold Tire Pressures: | LF <u>250</u> kPa | RF <u>250</u> kPa |
| | LR <u>250</u> kPa | RR <u>250</u> kPa |
| Wind Speed4.0 m/se (10m/sec (22mph) max for pass | | max. for MPVs and Trucks |
| Ambient Temperature (7°C (45°F | F) - 40°C (104°F))2 | <u>.1.7 °</u> °C |
| | | |
| Brake Conditioning Time | 12:00 PM | Date; 7-24-19 |
| 56 km/h (35 mph) Brake S | Stops | |
| Number of stops ex | xecuted (10 required) | 10 stops |
| Observed decelera | tion rate range (.5g target) | <u>0.47 – 0.51</u> g |
| 72 km/h (45 mph) Brake S | Stops | |
| Number of stops ex | xecuted (3 required) | 3 stops |
| Number of stops A | BS activated (3 required) | 3 stops |
| Observed decelera | tion rate range | <u>0.95 - 1.0</u> g |
| 72 km/h (45 mph) Brake (| Cool Down Period | |
| Duration of cool do | wn period (5 minutes min.) | 5.5 minutes |

DATA SHEET 6 (Sheet 2 of 3) BRAKE AND TIRE CONDITIONING

Tire Conditioning Series No. 1 Time: 12:20 PM Date: 7-24-19

Measured Tire Pressures: LF 260 kPa RF 260 kPa

LR 256 kPa RR 256 kPa

Wind Speed 3.1 m/sec
(10m/sec (22mph) max for passenger cars; 5m/s (11mph) max. for MPVs and Trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) 21.8 °C

| 30 meter (100 ft) Diameter Circle Maneuver | | | | | |
|---|------------------|---------|------|------|--|
| Test Runs Steering Direction Target Lateral Observed Lateral Observed Vehicle | | | | | |
| Acceleration (g) Acceleration (g) Speed (km/h) | | | | | |
| 1-3 | Clockwise | 0.5-0.6 | 0.54 | 45.9 | |
| 4-6 | Counterclockwise | 0.5-0.6 | 0.54 | 45.9 | |

| 1 Hz 5 Cycle Sinusoidal Steering Maneuver to Determine Steering Wheel Angle For 0.5-0.6g Lateral Acceleration | | | | | | | |
|---|-------------------------------|-----------------------------------|--------------------------------------|--|--|--|--|
| Test Runs | Vehicle Speed Km/h(mph) | Steering Wheel Angle (degrees) | Target Peak Lateral Acceleration (g) | Observed Peak Lateral Acceleration (g) | | | |
| 1 | 56 <u>+</u> 2 (35 <u>+</u> 1) | 30 | 0.5-0.6 | 0.27 | | | |
| 2 | 56 <u>+</u> 2 (35 <u>+</u> 1) | 60 | 0.5-0.6 | 0.49 | | | |
| 3 | 56 <u>+</u> 2 (35 <u>+</u> 1) | 70 | 0.5-0.6 | 0.57 | | | |
| 4 | 56 <u>+</u> 2 (35 <u>+</u> 1) | | 0.5-0.6 | | | | |

Steering wheel angle that corresponds to a peak 0.5–0.6g lateral acceleration; ______ degrees

| 1 Hz 10 Cycle Sinusoidal Steering Maneuver | | | | | | | | |
|--|-------------------------------|------------------|------------------|------------------|--|--|--|--|
| Test Runs | Vehicle Speed | Steering Wheel | Target Peak | Observed Peak | | | | |
| | Km/h (mph) | Angle (degrees) | Lateral | Lateral | | | | |
| | | | Acceleration (g) | Acceleration (g) | | | | |
| 1 - 3 | 56 <u>+</u> 2 (35 <u>+</u> 1) | 70 (cycles 1-10) | 0.5-0.6 | 0.57 | | | | |
| 4 | 56 <u>+</u> 2 (35 <u>+</u> 1) | 70 (cycles 1-9) | 0.5-0.6 | 0.57 | | | | |
| | | 140 (cycle 10)* | N/A | 0.78 | | | | |

^{*} The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9.

DATA SHEET 6 (Sheet 3 of 3) BRAKE AND TIRE CONDITIONING

| Tire Conditioning Series No. 2 | | | Time: 1:10 | PM | Dat | e: 7-24-19 | |
|--|--------------------------------|----------|-------------------------------|----------------------------|------|----------------------------------|--|
| Measured Tire P | ressures: L | .F .R | 270 kPa 265 kPa | RF RR | | kPa kPa | |
| | 4.5 m/sec h) max for passer | nger | cars; 5m/s (11 | Imph) max. fo | r MP | Vs and Trucks) | |
| Ambient Temperature (7°C (45°F) - 40°C (104°F)) °C | | | | | | | |
| 30 meter (100 ft) Diameter Circle Maneuver | | | | | | | |
| Test Runs | Steering Direction | | arget Lateral cceleration (g) | Observed Late Acceleration | | Observed Vehicle Speed (km/h) | |

| Hz 5 Cycle Sinusoidal Steering Maneuver to Determine Steering Wheel Angle For 0.5-0.6g Lateral Acceleration | | | | | | | |
|---|-------------------------------|-----------------------------------|--------------------------------------|--|--|--|--|
| Test Runs | Vehicle Speed Km/h (mph) | Steering Wheel Angle (degrees) | Target Peak Lateral Acceleration (g) | Observed Peak Lateral Acceleration (g) | | | |
| 1 | 56 <u>+</u> 2 (35 <u>+</u> 1) | N/A | 0.5-0.6 | N/A | | | |
| 2 | 56 <u>+</u> 2 (35 <u>+</u> 1) | | 0.5-0.6 | | | | |
| 3 | 56+2 (35+1) | | 0.5-0.6 | | | | |

0.5-0.6

0.5-0.6

0.54

0.54

0.5-0.6

45.9

45.9

Steering wheel angle that corresponds to a peak 0.5–0.6g lateral acceleration; ______ 70 ___degrees

| 1 Hz 10 Cycle Sinusoidal Steering Maneuver | | | | | | | | |
|--|-------------------------------|-----------------------------------|--------------------------------------|--|--|--|--|--|
| Test Runs | Vehicle Speed (mph) | Steering Wheel Angle (degrees) | Target Peak Lateral Acceleration (g) | Observed Peak Lateral Acceleration (g) | | | | |
| 1 - 3 | 56 <u>+</u> 2 (35 <u>+</u> 1) | 70 (cycles 1-10) | 0.5-0.6 | 0.57 | | | | |
| 4 | 56 <u>+</u> 2 (35 <u>+</u> 1) | 70 (cycles 1-9) | 0.5-0.6 | 0.57 | | | | |
| | | 140 (cycle 10)* | N/A | 0.78 | | | | |

^{*} The steering wheel angle used for cycle 10 should be twice the angle used for cycles 1-9.

1-3

4-6

4

clockwise

counterclockwise

56<u>+</u>2 (35<u>+</u>1)

| RECORDED BY: _ | David Karls | DATE: <u>7-30-19</u> |
|----------------|----------------|----------------------|
| APPROVED BY: _ | Jordan Piening | DATE: 7-30-19 |

DATA SHEET 7 (1 of 2) SLOWLY INCREASING STEER (SIS) MANEUVER

 VEHICLE NHTSA No.:
 C20190303
 TEST DATE:
 7-24-19

 Measured Tire Pressures:
 LF
 270
 kPa
 RF
 270
 kPa

 LR
 265
 kPa
 RR
 265
 kPa

Wind Speed _____ 3.1 _ m/sec (10m/sec (22mph) max for passenger cars; 5m/s (11mph) max. for MPVs and Trucks)

Ambient Temperature (7°C (45°F) - 40°C (104°F)) _____ 21.8 __ °C

VEHICLE MAKE/MODEL/BODY STYLE: RAM / 1500 / Truck

Selected Drive Configuration: RWD (default)

Selected Mode: ESC On (default)

Preliminary Left Steer Maneuver:

Lateral Acceleration measured at 30 degrees steering wheel angle (a_{y,30 degrees})

$$a_{y,30 \text{ degrees}} = \underline{0.32 \text{ g}}$$

Assuming a linear relationship the following ratio should be used to calculate the steering wheel angle at .55g.

$$\frac{30 \text{ degrees}}{a_{\text{y,30degrees}}} = \frac{\delta_{\text{S/S}}}{0.55 \text{ g}}$$

$$\frac{\delta_{\text{S/S}} = \underline{51.6} \text{ degrees @ 0.55g}}{\delta_{\text{S/S}} = \underline{60} \text{ degrees (rounded)}}$$

Steering Wheel Angle at Corrected 0.3 g Lateral Acceleration:

| Maneuver # | Initial Steer Direction | Time Clock (5 min max between runs) | Steering Wheel Angle to nearest 0.1 degree (degrees) | All Conditions Met? |
|---------------|----------------------------|---|--|---------------------------|
| 0006 | Left | 12:37 pm | -35.2 | Yes |
| 0008 | Left | 12:42 pm | -35.4 | Yes |
| 0009 | Left | 12:43 pm | -35.6 | Yes |
| 0010 | Right | 12:45 pm | 34.1 | Yes |
| 0011 | Right | 12:46 pm | 35.2 | Yes |
| 0012 | Right | 12:48 pm | 35.0 | Yes |

DATA SHEET 7 (2 of 2) SLOWLY INCREASING STEER (SIS) MANEUVER

Average Overall Steering Wheel Angle:

$$\delta_{0.3 \text{ g, overall}} = \left(\left\| \delta_{0.3 \text{ g, left (1)}} \right\| + \left\| \delta_{0.3 \text{ g, left (2)}} \right\| + \left\| \delta_{0.3 \text{ g, left (3)}} \right\| + \delta_{0.3 \text{ g, right (1)}} + \delta_{0.3 \text{ g, right (2)}} + \delta_{0.3 \text{ g, right (3)}} \right) / 6$$

$$\delta_{0.3 \text{ g, overall}} = \underline{35.1}$$
 degrees [to nearest 0.1 degree]

REMARKS:

 RECORDED BY:
 David Karls
 DATE: 7-30-19

 APPROVED BY:
 Jordan Piening
 DATE: 7-30-19

DATA SHEET 8 (1 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

| VEHICLE MAKE/MODEL/BODY | STYLE: RAI | M / 1500 / Truck | |
|--|---------------------|------------------------------|----|
| VEHICLE NHTSA No.: C20190 | 303 TEST | DATE: 7-24-19 | _ |
| Tire conditioning completed ESC system is enabled On track calibration checks have On track static data file for each | | XYes XYes XYes XYes | Nc |
| Selected Drive Configuration: Selected Mode: | RWD ESC On (defa | ult) | |
| Overall steering wheel angle (δ_0 | 3 g. overall)35.1 | degrees | |

Lateral Stability Test Series No. 1 - Counterclockwise Initial Steer Direction

| | Clock Time | Comman Steering W Angle | /heel | | Yaw Rate (degrees/s | - | at 1.0 s | RR ec after DS | at 1.75 | RR sec after OS |
|---------------|-------------------------------------|-------------------------------|-------|-------------------|------------------------|----------------------|----------|----------------------|---------|-----------------------|
| | (1.5 – 5 | (degree | | ' | (4.09.000,0 | | | 5%] | | 20%] |
| Maneuver # | min between each test run) | Scalar | Angle | Ψ _{Peak} | Ψ _{1.0sec} | Ψ _{1.75sec} | % | Pass/ Fail | % | Pass/ Fail |
| 0014 | 1:13 pm | 1.5* δ0.3 g | 53 | 12.542 | 0.089 | 0.532 | 0.710 | Pass | 4.244 | Pass |
| 0015 | 1:15 pm | 2.0* δ0.3 g | 70 | 14.525 | -0.096 | 0.183 | -0.661 | Pass | 1.262 | Pass |
| 0016 | 1:17 pm | 2.5* δ0.3 g | 88 | 17.802 | -0.140 | 0.477 | -0.788 | Pass | 2.678 | Pass |
| 0017 | 1:19 pm | 3.0* δ0.3 g | 105 | 21.411 | -0.162 | 0.499 | -0.757 | Pass | 2.329 | Pass |
| 0018 | 1:22 pm | 3.5* δ0.3 g | 123 | 24.459 | -0.206 | 0.417 | -0.842 | Pass | 1.704 | Pass |
| 0019 | 1:24 pm | 4.0* δ0.3 g | 140 | 24.983 | -0.013 | 0.188 | -0.052 | Pass | 0.752 | Pass |
| 0020 | 1:26 pm | 4.5* δ0.3 g | 158 | 27.151 | -0.176 | 0.310 | -0.648 | Pass | 1.143 | Pass |
| 0021 | 1:29 pm | 5.0* δ0.3 g | 176 | 28.190 | -0.140 | 0.213 | -0.495 | Pass | 0.757 | Pass |
| 0022 | 1:31 pm | 5.5* δ0.3 g | 193 | 27.402 | -0.142 | 0.116 | -0.519 | Pass | 0.425 | Pass |
| 0023 | 1:34 pm | 6.0* δ0.3 g | 211 | 27.770 | 0.025 | 0.082 | 0.091 | Pass | 0.296 | Pass |
| 0024 | 1:37 pm | 6.5* δ0.3 g | 228 | 29.104 | 0.026 | 0.260 | 0.091 | Pass | 0.892 | Pass |
| 0025 | 1:40 pm | 7.0* δ0.3 g | 246 | 29.010 | -0.149 | 0.094 | -0.512 | Pass | 0.325 | Pass |
| 0026 | 1:43 pm | 7.5* δ0.3 g | 263 | 30.898 | 0.100 | 0.286 | 0.325 | Pass | 0.925 | Pass |
| 0027 | 1:47 pm | 7.7* δ0.3 g | 270 | 31.272 | -0.069 | -0.078 | -0.222 | Pass | -0.249 | Pass |
| | | | | | | | | | | |
| | | | | | | | | | | |
| | | | | | | | | | | |
| | | | | | | | | | | |
| | | | | | | | | | | |
| | | | | | | | | | | |
| | | | | | | | | | | |

^{1.} Maneuver execution should continue until a steering wheel angle magnitude factor of 6.5*\dark_{0.3 g, overall} or 270 degrees is utilized, whichever is greater provided the calculated magnitude of 6.5*\dark_{0.3 g, overall} is less than or equal to 300 degrees. If 6.5*\dark_{0.3 g, overall} is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of 0.5*\dark_{0.3 g, overall} without exceeding the 270 degree steering wheel angle.

DATA SHEET 8 (2 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

Lateral Stability Test Series No. 2 - Clockwise Initial Steer Direction

| | Clock | Comman | ded | | | | YF | ₹R | Y | RR |
|----------|----------------------|--------------------|-------|---------------|------------------------|-------------------------|-----------------|--|-----------------|---------------|
| | Time | Steering W | /heel | | Yaw Rate | s | at 1.0 s | ec after | at 1.75 | sec after |
| | | Angle ¹ | l | (| (degrees/s | ec) | CC | os - | C | OS |
| | (1.5 - 5) | (degree | s) | | | | [<u><</u> 3 | 5%] | [<u><</u> 2 | 20%] |
| Maneuver | min | | | | | | | | | |
| # | between each test | Scalar | Angle | ψ_{Peak} | $\Psi_{\text{1.0sec}}$ | $\psi_{1.75\text{sec}}$ | % | Pass/ Fail | % | Pass/ Fail |
| | run) | | | | | | | | | |
| 0028 | 1:49 pm | 1.5* δ0.3 g | 53 | -12.199 | -0.126 | 0.012 | 1.030 | Pass | -0.095 | Pass |
| 0029 | 1:52 pm | 2.0* δ0.3 g | 70 | -15.768 | 0.084 | 0.401 | -0.531 | Pass | -2.543 | Pass |
| 0030 | 1:54 pm | 2.5* δ0.3 g | 88 | -18.589 | -0.118 | 0.778 | 0.634 | Pass | -4.184 | Pass |
| 0031 | 1:57 pm | 3.0* δ0.3 g | 105 | -21.449 | 0.209 | 0.467 | -0.976 | Pass | -2.176 | Pass |
| 0032 | 1:59 pm | 3.5* δ0.3 g | 123 | -24.848 | 0.292 | 0.659 | -1.175 | Pass | -2.652 | Pass |
| 0033 | 2:01 pm | 4.0* δ0.3 g | 140 | -25.354 | 0.374 | 0.109 | -1.476 | Pass | -0.431 | Pass |
| 0034 | 2:04 pm | 4.5* δ0.3 g | 158 | -27.083 | 0.317 | 0.479 | -1.171 | Pass | -1.770 | Pass |
| 0035 | 2:07 pm | 5.0* δ0.3 g | 176 | -28.969 | 0.343 | -0.072 | -1.184 | Pass | 0.248 | Pass |
| 0036 | 2:09 pm | 5.5* δ0.3 g | 193 | -28.533 | 0.252 | 0.142 | -0.882 | Pass | -0.498 | Pass |
| 0037 | 2:11 pm | 6.0* δ0.3 g | 211 | -29.763 | 0.251 | -0.119 | -0.844 | Pass | 0.400 | Pass |
| 0038 | 2:13 pm | 6.5* δ0.3 g | 228 | -29.448 | 0.078 | -0.064 | -0.264 | Pass | 0.218 | Pass |
| 0039 | 2:16 pm | 7.0* δ0.3 g | 246 | -30.278 | 0.407 | 0.224 | -1.343 | Pass | -0.739 | Pass |
| 0040 | 2:18 pm | 7.5* δ0.3 g | 263 | -30.413 | 0.000 | 0.155 | -0.001 | Pass | -0.511 | Pass |
| 0041 | 2:21 pm | 7.7* δ0.3 g | 270 | -30.335 | 0.066 | -0.019 | -0.218 | Pass | 0.061 | Pass |
| | | | | | | | | | | |
| | | | | | | | | | | |
| Managera | | | | | | | | 24 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 | | |

^{1.} Maneuver execution should continue until a steering wheel angle magnitude factor of 6.5*\delta_{0.3 g, overall} or 270 degrees is utilized, whichever is greater provided the calculated 6.5*\delta_{0.3 g, overall} or 270 degrees is utilized, whichever is greater provided the calculated 6.5*\delta_{0.3 g, overall} is less than or equal to 300 degrees. If 6.5*\delta_{0.3 g, overall} is less than 270 degrees maneuver execution should continue by increasing the steering wheel angle magnitude by multiples of 0.5*\delta_{0.3 g, overall} without exceeding the 270 degree steering wheel angle.

| During execution of the sine with dwell maneuvers were | e any of the following events observed? |
|--|---|
| Rim-to-pavement contact | Yes <u>X</u> No |
| Tire debeading | Yes <u>X</u> No |
| Loss of pavement contact of vehicle tires | Yes <u>X</u> No |
| Did the test driver experience any vehicle loss of control or spinout? | Yes <u>X</u> No |
| If "Yes" explain the event and consult with the COTR. | |
| • | |

DATA SHEET 8 (3 of 3) VEHICLE LATERAL STABILITY AND RESPONSIVENESS

Responsiveness - Lateral Displacement

| | | Commanded Steer | ing Wheel Angle | Calculated Lateral Displacement ¹ | | |
|---------------|----------------------------|--|--------------------|--|-----------|--|
| | | $(5.0^*\delta_{0.3 \text{ g, overall}})$ | or greater) | · | | |
| Maneuver # | Initial Steer Direction | Scalar | Angle (degrees) | Distance (m) | Pass/Fail | |
| 0021 | Counter Clockwise | 5.0* δ0.3 g | 176 | -2.70 | Pass | |
| 0022 | Counter Clockwise | 5.5* δ0.3 g | 193 | -2.72 | Pass | |
| 0023 | Counter Clockwise | 6.0* δ0.3 g | 211 | -2.70 | Pass | |
| 0024 | Counter Clockwise | 6.5* δ0.3 g | 228 | -2.69 | Pass | |
| 0025 | Counter Clockwise | 7.0* δ0.3 g | 246 | -2.74 | Pass | |
| 0026 | Counter Clockwise | 7.5* δ0.3 g | 263 | -2.70 | Pass | |
| 0027 | Counter Clockwise | 7.7* 80.3 g | 270 | -2.75 | Pass | |
| | | | | | | |
| | | | | | | |
| 0035 | Clockwise | 5.0* δ0.3 g | 176 | 2.53 | Pass | |
| 0036 | Clockwise | 5.5* δ0.3 g | 193 | 2.62 | Pass | |
| 0037 | Clockwise | 6.0* δ0.3 g | 211 | 2.57 | Pass | |
| 0038 | Clockwise | 6.5* δ0.3 g | 228 | 2.55 | Pass | |
| 0039 | Clockwise | 7.0* δ0.3 g | 246 | 2.53 | Pass | |
| 0040 | Clockwise | 7.5* δ0.3 g | 263 | 2.59 | Pass | |
| 0041 | Clockwise | 7.7* δ0.3 g | 270 | 2.58 | Pass | |
| | | | | | | |
| | | | | | | |

| teral displacement should be ≥ 1.83 m (6 ft) for vehicles with a GVVVR of 3,500 kg (7,716 lb) of le | ess; and \geq 1.52 m (5ft) for venicles with | a GVVVR greater than 3,500 kg (7,71) |
|--|--|--------------------------------------|
| DATA INDICATES COMPLIANCE: | PASS/FAIL | PASS |
| REMARKS. | | |

| RECORDED BY: | David Karls | DATE: | 7-30-19 |
|--------------|----------------|-------|---------|
| APPROVED BY: | Jordan Piening | DATE: | 7-30-19 |

DATA SHEET 9 (Sheet 1 of 6) MALFUNCTION WARNING TEST (Test Number 1)

| VEHICLE MAKE/MODEL | _/BODY STYLE: _ | RAM / | / 1500 / Trud | <u>ck</u> | |
|--|--|--------------|----------------------|-------------|-------------------------|
| VEHICLE NHTSA No.:_ | C20190303 | TEST | DATE: | 7-24-19 | |
| METHOD OF MALFUNG Describe method of malf | | | | | |
| Remove the | <u>e 50A fuse (F26) fo</u> | r the ESC | Module. | | |
| MALFUNCTION TELLTATE Telltale illuminates and r if necessary the vehicle i | emains illuminated | after ignit | _ | section 13 | 3.12. B. |
| Telltale illuminated when | engine was started | d, no drivir | ng required. XYes | s (Pass) _ | No |
| Driving was required to il | luminate telltale. | | Yes | _ | X_No |
| When driving was require (30 <u>+</u> 5mph) was reached | l. | | vehicle spe | | |
| If driving required, (30 <u>+</u> 5mph) to act | approximate drivin ivate telltale. | • | low vehicle | speed of 48 | 3 <u>+</u> 8 km/h |
| When driving was require (30 <u>+</u> 5mph) was reached | l. ['] | | vehicle spe | | 8 <u>+</u> 8 km/h No |
| • | time for telltale to i of 48 <u>+</u> 8 km/h (30 <u>-</u> | | | g system is | activated |
| Seconds (| must be within 2 mi | nutes) | | Pass | Fail |

DATA SHEET 9 (Sheet 2 of 6) MALFUNCTION WARNING TEST (Test Number __1_)

| Identify all other telltales and/or warning m | essages a | ctivated upon simu | llating subject |
|--|-------------|------------------------------|-----------------------|
| ESC system malfunction. ESC, ABS, and | Parking B | rake telltales illum | inated. |
| Service Anti-Lock Brake System and Servi | ce Electro | nic Stability Contro | l messages also |
| displayed. | | | |
| | | | |
| | | | |
| Did the malfunction telltale re-illuminate aft minutes and then turned back on with the | | 0 , | nut off for five |
| | X | _Yes (Pass) | No (Fail) |
| ESC SYSTEM RESTORATION: Describe method used to restore system to | o normal o | peration: | |
| Replace the 50A fuse. | | | |
| After system restoration is completed, tellto is activated and if necessary the vehicle is section 13.12. D. | | | specified in |
| Telltale extinguished when engine was sta | rted, no dr | iving required. XYes (Pas | s)No |
| Driving was required to extinguish telltale. | | Yes | XNo |
| When driving was required, telltale extingu (30± 5mph) was reached. | ished befo | re vehicle speed o | f 48 <u>+</u> 8 km/h |
| | X_NA | Yes (Pas | ss)No |
| If driving required, approximate drivi (30± 5mph) to extinguish telltale. | ing time be | · | of 48 <u>+</u> 8 km/h |
| | | Seconds | |

DATA SHEET 9 (Sheet 3 of 6) MALFUNCTION WARNING TEST (Test Number __1_)

| When driving was required, telltale extinguished after a vehicle speed above 48± 8 km/ | | | | | | |
|--|----------|-------|----------------------|--------------|--|--|
| (30± 5mph) was reached. | _ | NA | - | No | | |
| | | | | | | |
| If driving required, time for telltale and vehicle speed of 48±8 km/h | | | | is activated | | |
| Seconds (must be within 2 | 2 minute | s) | Pass | Fail | | |
| | | | | | | |
| | | | | | | |
| DATA INDICATES COMPLIANCE: | | | PASS/FAIL _ | PASS | | |
| REMARKS: | | | | | | |
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| | | | | | | |
| DECORDED DV. D. CHK. I. | | D 4 T | - 700 | 40 | | |
| RECORDED BY: <u>David Karls</u> APPROVED BY: <u>Jordan Piening</u> | | | E: 7-30⋅ E: 7-30⋅ | | | |

DATA SHEET 9 (Sheet 4 of 6) MALFUNCTION WARNING TEST (Test Number 2

| VEHICLE MAKE/MODEL | _/BODY STYLE: _ | RAM | <u>/ 1500 / Truc</u> | <u>ck</u> | |
|--|---|-------------|-----------------------|--------------|-------------------------|
| VEHICLE NHTSA No.:_ | C20190303 | TEST | DATE: | 7-24-19 | |
| METHOD OF MALFUNG Describe method of malf | | | | _ | |
| Disconnect the lef | t rear wheel speed | sensor | | | |
| MALFUNCTION TELLTATE Telltale illuminates and r if necessary the vehicle i | emains illuminated | after igni | | section 13 | .12. B. |
| Telltale illuminated when | engine was started | d, no drivi | ng required. X Yes | s (Pass) _ | No |
| Driving was required to il | luminate telltale. | | Yes | <u> </u> | X_No |
| When driving was require (30 <u>+</u> 5mph) was reached | l. | | vehicle spe | _ | |
| If driving required, (30 <u>+</u> 5mph) to act | approximate drivin ivate telltale. | | elow vehicle s | speed of 48 | ± 8 km/h |
| When driving was require (30 <u>+</u> 5mph) was reached | l. ['] | | vehicle spe | | 3 <u>+</u> 8 km/h No |
| • | time for telltale to i of 48 <u>+</u> 8 km/h (30 | | | g system is | activated |
| Seconds (| must be within 2 mi | nutes) | | Pass | Fail |

DATA SHEET 9 (Sheet 5 of 6) MALFUNCTION WARNING TEST (Test Number __2_)

| Identify all other telltales and/or warning | messages acti | vated upon simulat | ing subject | | |
|---|-----------------------|----------------------|--------------------|--|--|
| SC system malfunction. ESC, ABS, and Parking Brake telltales illuminated. | | | | | |
| Service Anti-Lock Brake Sy | stem, Service | Electronic Stability | Control, and | | |
| 4WD System Temporarily U | Jnavailable me | essages also displa | yed. | | |
| | | | | | |
| Diddle and Konstinut alled a confined and | effect discount and a | | | | |
| Did the malfunction telltale re-illuminate | | 9 | off for five | | |
| minutes and then turned back on with the | e engine runnir | ng? | | | |
| | X | Yes (Pass) | _No (Fail) | | |
| | | | | | |
| ESC SYSTEM RESTORATION: Describe method used to restore system | to normal ope | ration: | | | |
| Reconnect the left rear wheel spe | ed sensor | | | | |
| After system restoration is completed, te is activated and if necessary the vehicle section 13.12. D. | • | | ecified in | | |
| Telltale extinguished when engine was s | tarted. no drivi | na required. | | | |
| | | X Yes (Pass) | No | | |
| Driving was required to extinguish telltale | e. <u>-</u> | Yes | XNo | | |
| When driving was required, telltale exting (30± 5mph) was reached. | guished before | vehicle speed of 4 | 8 <u>+</u> 8 km/h | | |
| () | X_NA | Yes (Pass) | No | | |
| If driving required, approximate dr (30± 5mph) to extinguish telltale. | iving time belo | w vehicle speed of | 48 <u>+</u> 8 km/h | | |
| | | Seconds | | | |

3.0 TEST DATA....continued

DATA SHEET 9 (Sheet 6 of 6) MALFUNCTION WARNING TEST (Test Number __2_)

| When driving was required, telltale extinguished after (30± 5mph) was reached. | a veł | nicle spee | ed above | 48 <u>+</u> 8 km/h |
|---|------------|------------|------------------|--------------------|
| X | _NA | | Yes _ | No |
| If driving required, time for telltale to extinguish and vehicle speed of 48+ 8 km/h (30+ 5mph) i | | | system i | s activated |
| Seconds (must be within 2 minutes) | | | Pass _ | Fail |
| | | | | |
| DATA INDICATES COMPLIANCE: | | PASS/ | FAIL | PASS |
| REMARKS: | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| RECORDED BY: David Karls APPROVED BY: Jordan Piening | DAT DAT | | 7-30-1 7-30-1 | |

4.0 TEST EQUIPMENT LIST AND CALIBRATION INFORMATION

| Туре | Output | Range | Resolution | Accuracy | Specifics | Serial Number | Calibration |
|---|---|---|---|---|---|----------------------------|--|
| Tire Pressure Gauge | Vehicle Tire Pressure | 0-99 psi | 0.01 psi | ±0.5% of applied pressure | Intercomp 360045-150-BC | <u>AG-</u> 0422SS08645 | By:TRC Inc. Date:6-10-19 Due:12-10-19 |
| Platform Scales | Vehicle Total, Wheel, and Axle Load | 0-2500 lb per each of four pads | 0.5 lb | ±1.0% of applied load | Mettler Toledo Model: JXGA1000 | <u>5225831-5JC</u> | By: <u>Mettler Toledo</u> Date: <u>5-29-19</u> Due: <u>8-30-19</u> |
| Automated Steering Machine with Steering Angle Encoder | Handwheel Angle | ±800 deg | 0.25 deg | ±0.25 deg | Heitz Automotive Testing Model: Sprint 3 | 60303 | By: <u>ATI-Heitz</u> Date: <u>2-1-19</u> Due: <u>2-1-20</u> |
| Multi-Axis Inertial Sensing System | Longitudinal, Lateral, and Vertical Acceleration Roll, Yaw, and Pitch Rate | Accelerom eters: ±2 g Angular Rate Sensors: ±100 deg/s | Acceleromet ers: ≤10 ug Angular Rate Sensors: ≤0.004 deg/ s | Acceleromete rs: ≤0.05% of full range Angular Rate Sensors: 0.05% of full range | BEI Technologies Model: MotionPAK MP-1 | <u>0767</u> | By: <u>BEI Tech.</u> Date: <u>1-30-19</u> Due: <u>1-30-20</u> |
| Radar Speed Sensor and Dashboard Display | Vehicle Speed | 0-125 mph | 0.009 mph | ±0.25% of full scale | A-DAT Corp. Radar Model: DRS-6 Display Model: RD-2 | <u>1400603</u> | By: TRC Inc. Date: 5-20-19 Due: 5-20-20 |
| Laser Height / Body Roll Measuring System | Left and Right Side Vehicle Height | 150 to 900 mm | 0.3 mm | ±0.3% | Kistler Model: HF-750C | _078-11249 & 078-11250_ | By: _TRC Inc Date: _ 3-13-19 Due: _ 3-13-20 |
| Data Acquisition System [Amplify, Anti- Alias, and Digitize] | Record Time; Velocity; Distance; Lateral, Longitudinal, and Vertical Accelerations; Roll, Yaw, and Pitch Rates; Steering Wheel Angle. | Sufficient to meet or exceed individual sensors | 200 Hz | Sufficient to meet or exceed individual sensors | Dewetron Sidehand DAS Model: DA- 121 Digitizer Model: Dewe-Orion- 1616-100 Amplifier/AntiAlia sing: MDAQ- FILT-10-S | 101031009 | By:TRC Inc Date:3-20-19 Due:3-20-20 |
| Load Cell | Vehicle Brake Pedal Force | 0-300 lb | 1 lb | ±0.05% of full scale | DATRON Model: DTM- LPA | _4970-1103_ | By:TRC Inc Date: _per test Due: _per test |
| Coordinate Measurement Machine | Inertial Sensing System Location | 0-10 feet | 0.001 inch | ±0.003% of full scale | FARO International Model: Faro Advantage | _C12-05-06- _04829_ | By:FARO Date:9-19-18 Due:9-19-19 |
| Outriggers | No output. Safety Item. | N/A | N/A | N/A | NHTSA Titanium Outriggers Model: Docket 2007-27662-11 | Asset ID: 70725 | N/A |
| Weather Station | Temperature and Wind Speed | -40-150°F 0-200mph | 0.1°F 1mph | ±1°F ±2mph | Davis Instruments Vantage Pro2 | <u>070817N01</u> | By: Davis Inst Date: 4-1-19 Due: 4-1-20 |

5.0 PHOTOGRAPHS

- 5.1 % FRONT VIEW FROM LEFT SIDE OF VEHICLE
- 5.2 34 REAR VIEW FROM RIGHT SIDE OF VEHICLE
- 5.3 VEHICLE CERTIFICATION LABEL
- 5.4 TIRE AND LOADING INFORMATION LABEL
- 5.5 WINDOW STICKER (MONRONEY LABEL)
- 5.6 ESC OFF AND ESC MALFUNCTION TELLTALES
- 5.7 ESC OFF CONTROL LOCATION
- 5.8 ESC OFF CONTROL
- 5.9 3/4 FRONT VIEW TEST VEHICLE INSTRUMENTED
- 5.10 34 REAR VIEW TEST VEHICLE INSTRUMENTED
- 5.11 STEERING WHEEL CONTROLLER AND DATA ACQUISITION SYSTEM
- 5.12 STEERING CONTROLLER BATTERY BOX
- 5.13 INERTIA MEASUREMENT UNIT
- 5.14 VEHICLE SPEED SENSOR
- 5.15 BODY ROLL SENSOR (DRIVER SIDE)
- 5.16 BODY ROLL SENSOR (PASSENGER SIDE)
- 5.17 BRAKE PEDAL FORCE TRANSDUCER







FMVSS 126

VEHICLE No.: C20190303

July 2019



TIRE AND LOADING INFORMATION

SEATING CAPACITY - TOTAL 6

FRONT

3 REAR

3

THE COMBINED WEIGHT OF OCCUPANTS AND CARGO SHOULD NEVER EXCEED

815 KG OR 1798 LB

| TIRE | FRONT | REAR | SPARE |
|------------------------------|------------------|------------------|------------------|
| ORIGINAL TIRE SIZE | 275/65R18 116T | 275/65R18 116T | 245/70R18 110S |
| COLD TIRE INFLATION PRESSURE | 250 kPa / 36 PSI | 250 kPa / 36 PSI | 310 kPa / 45 PSI |

SEE OWNERS MANUAL FOR ADDITIONAL INFORMATION



KN552167

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FMVSS 126

VEHICLE No.: C20190303





2019 MODEL YEAR

RAM 1500 TRADESMAN CREW CAB 4X4

EXTERIOR FEATURES

275/65R18 BSW All-Season Tires 18-Inch Full Size Steel Spare Wheel

Customer Preferred Package 25A

Chrome Appearance Group

Tradesman Chrome Grille

Cloth 40 / 20 / 40 Bench Seat

Front and Rear Floor Mats

Rear Power Sliding-Window

Three Rear Seat Head Restraints

5.7-Liter V8 HEMI® MDS VVT Engine

Anti-Spin Differential Rear Axle

Active Noise-Control System

Class IV Receiver-Hitch

DESTINATION CHARGE

WARRANTY COVERAGE

Level 1 Equipment Group

Carpet Floor Covering

Bright Front Bumper

Bright Rear Bumper

Automatic Headlamps Halogen Quad Headlamps

Cargo Tie-Down Loops

Locking Tailgate

18.0-Inch x 7.5-Inch Steel Painted Wheels

Power-Heated Mirrors with Manual Fold-Away

OPTIONAL EQUIPMENT (May Replace Standard Equipment)

18.0-Inch x 8.0-Inch Premium Paint Cast Wheels

SiriusXM® Sat Radio w/ 1-Yr Sub Call 800-643-2112

TOTAL PRICE: * \$44,165

5-year or 60.000-mile Powertrain Limited Warranty.

3-year or 36,000-mile Basic Limited Warranty.

see your owner's manual for details.

Ask Dealer for a copy of the limited warranties or

5YEAR /60,000 MILE

POWERTRAIN WARRANTY

THIS VEHICLE IS MANUFACTURED TO MEET SPECIFIC UNITED STATES REQUIREMENTS. THIS VEHICLE IS NOT MANUFACTURED FOR SALE OR REGISTRATION OUTSIDE OF THE UNITED STATES.

MANUFACTURER'S SUGGESTED RETAIL PRICE OF THIS MODEL INCLUDING DEALER PREPARATION

Base Price: \$37,995

RAM 1500 TRADESMAN CREW CAB 4X4

Exterior Color: Bright White Clear-Coat Exterior Paint Interior Color: Black Interior Color

Interior: Cloth 40 / 20 / 40 Bench Seat Engine: 5.7-Liter V8 HEMI® MDS VVT Engine Transmission: 8-Speed Automatic 8HP75 Transmission

STANDARD EQUIPMENT (UNLESS REPLACED BY OPTIONAL EQUIPMENT)
FUNCTIONAL/SAFETY FEATURES

Advanced Multistage Front Air Bags Supplemental Front Seat Side Air Bags Supplemental Side-Curtain Front / Rear Air Bags

3.21 Rear Axle Ratio Keyless Go™

40

Remote Keyless Entry with All-Secure Parkview® Rear Back-Up Carnera

Sentry Key® Theft Deterrent System 4-Wheel Disc Anti-Lock Brakes Electric Park Brake

Ready-Alert Braking Rain Brake Support

Tire-Fill Alert Electronic Roll Mitigation

Electronic Stability Control Trailer Sway Damping Hill Start Assist

Speed Control Black Rotary Shifter

Class III Receiver-Hitch 7-Pin Wiring Harness

Capless Fuel-Fill

INTERIOR FEATURES Uconnect® 3 with 5-Inch Display Cluster 3.5-Inch TFT B&W Display

Integrated Voice Command with Bluetooth® Media Hub-2 USB, Full Function, Aux

12-Volt Auxiliary Power Outlet

6-Speakers

4-Way Manual Adjustable Driver Seat Front Passenger Seat - Manual Adjust 4-Way

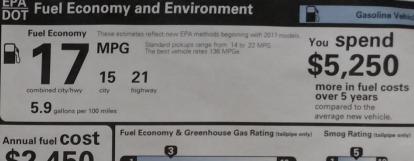
Power Windows w/ Front 1-Touch Up and Down Feature

Tilt/Telescope Steering Column

Assembly Point/Port of Entry: STERLING HTS, MICH., U.S.A.

For more information visit: www.ramtrucks.com or call 1-866-RAMINFO

FCA US LLC



\$2,450

tual results will vary for many reasons, including driving conditions and how you drive and maintain you hide. The average new vehicle gets 27 MPG and cost \$7,000 to fuel over 5 years. Cost estimates are ead on 15,000 miles per year at \$2.80 per gallon. MPGe is miles per gasoline gallon equivalent. Vehicle hissions are a significant cause of climate change and smog.

fueleconomy.gov





GOVERNMENT 5-STAR SAFETY RATINGS

This vehicle has not been rated by the government for frontal crash, side crash or rollover risk.

Source: National Highway Traffic Safety Administration (NHTSA) www.safercar.gov or 1-888-327-4236

PARTS CONTENT INFORMATION FOR VEHICLES IN THIS CARLINE: U.S./CANADIAN PARTS CONTENT: 57% MAJOR SOURCES OF FOREIGN PARTS CONTENT: MEXICO: 28% NOTE: PARTS CONTENT DOES NOT INCLUDE FINAL ASSEMBLY, DISTRIBUTION, OR OTHER

FOR THIS VEHICLE: FINAL ASSEMBLY POINT: STERLING HTS, MICH., U.S.A.

COUNTRY OF ORIGIN: ENGINE: MEXICO TRANSMISSION: UNITED STATES





2nd-Row In-Floor Storage Bins Front / Rear Climate-Control Outlets

Steering Wheel Mounted Shift Control

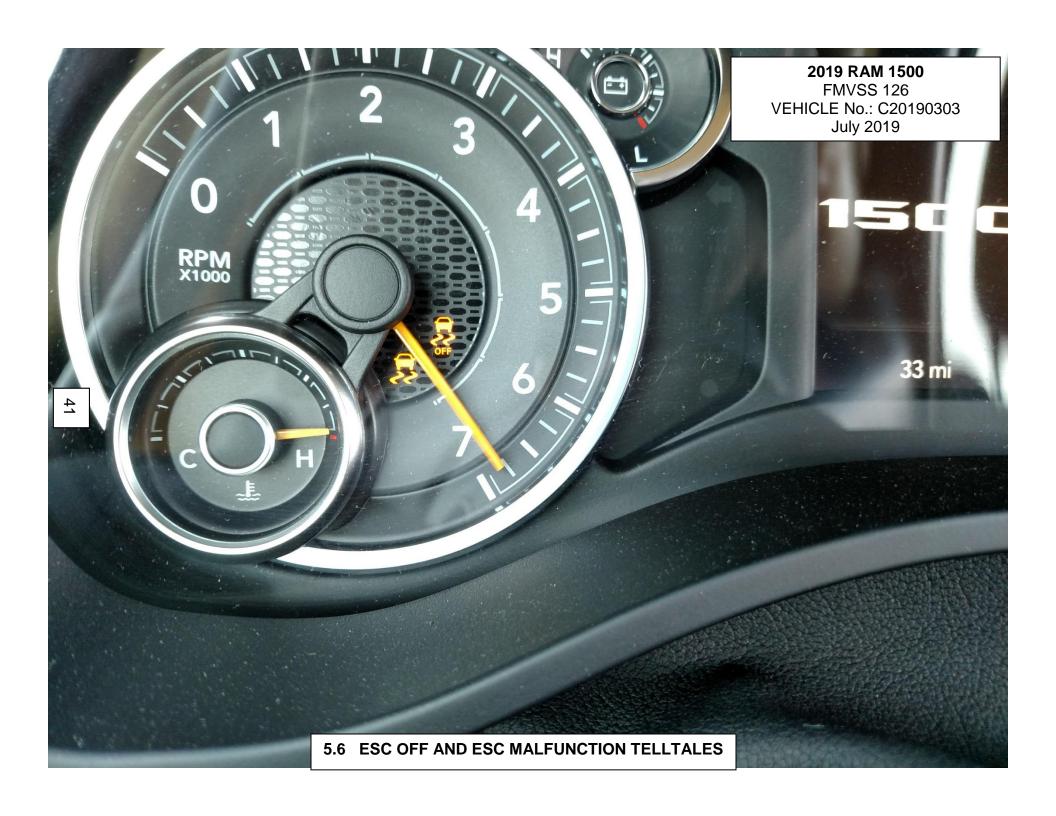
\$1,555

\$435

\$1,195

\$345

\$1.645



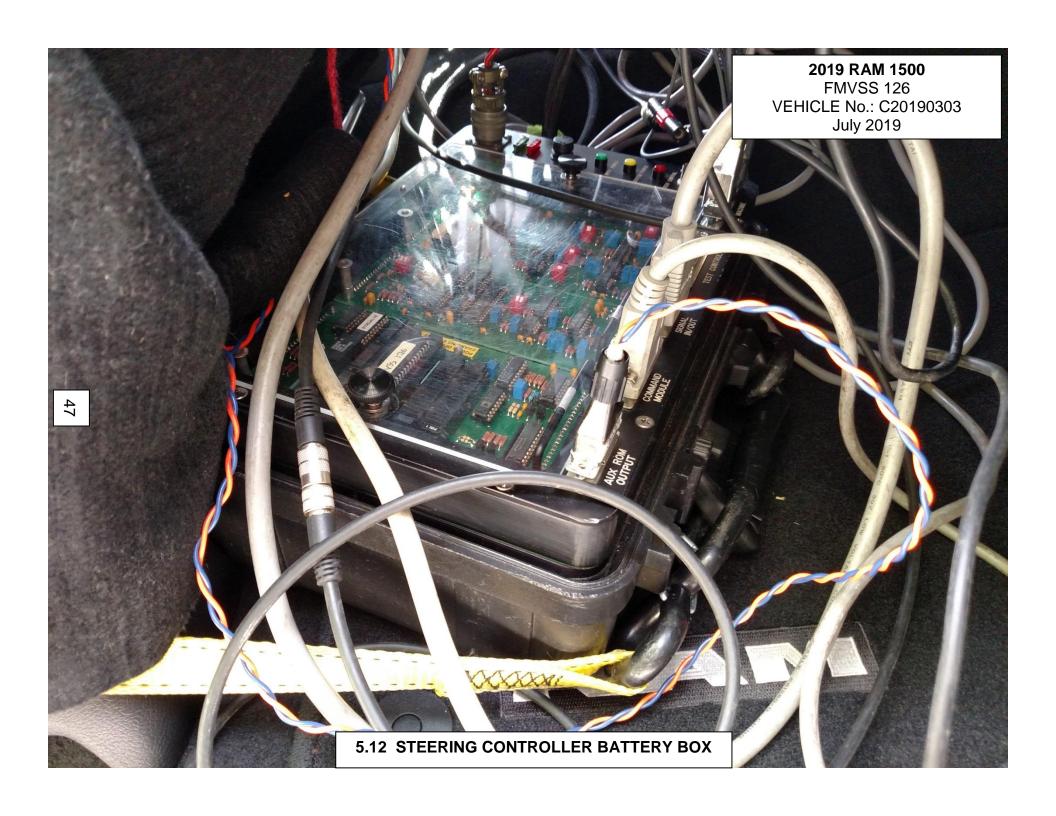






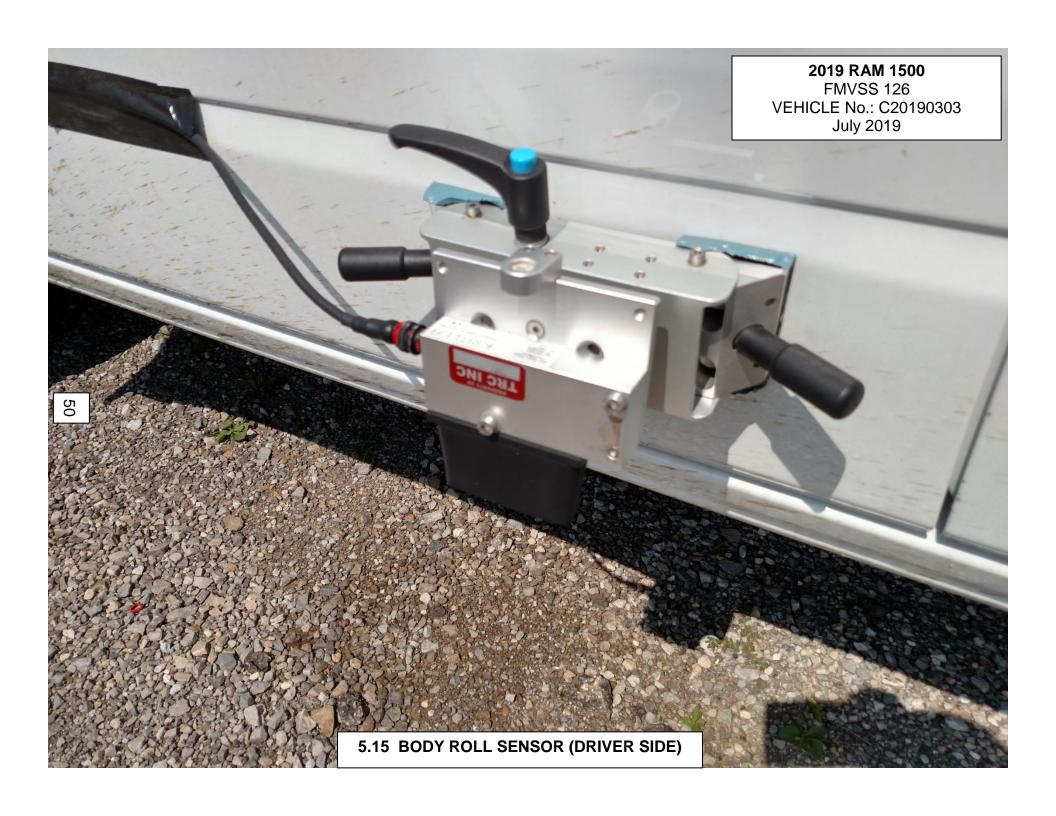




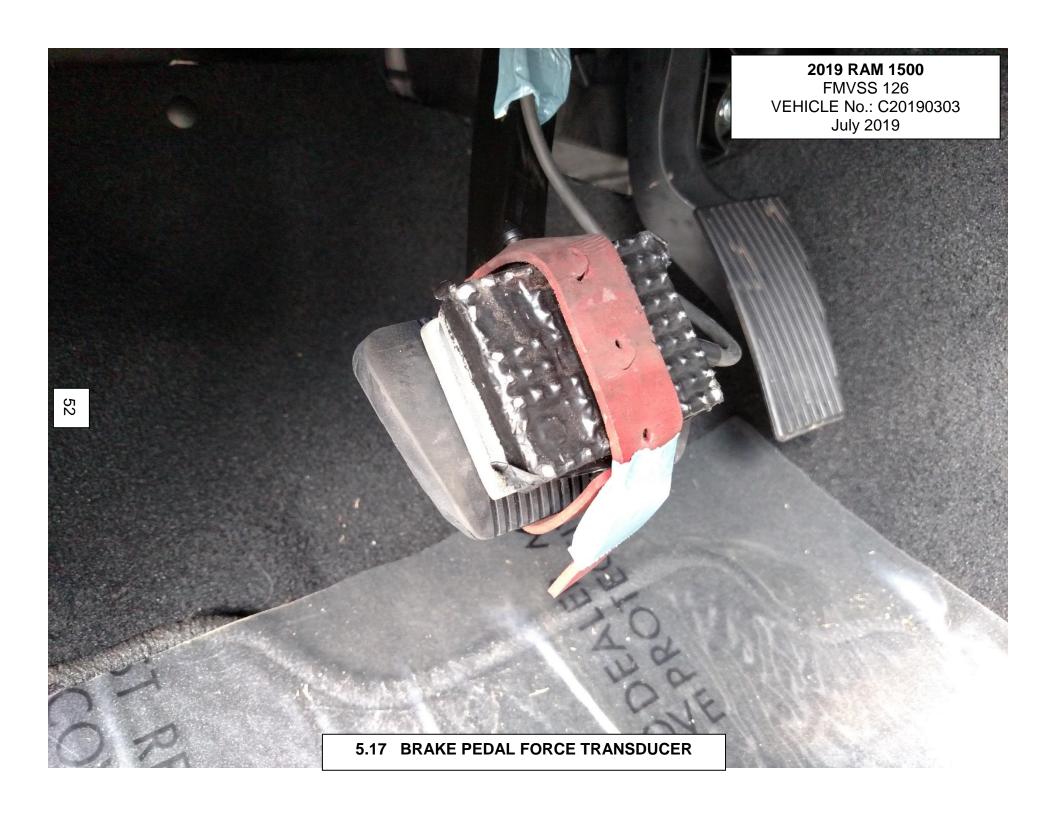










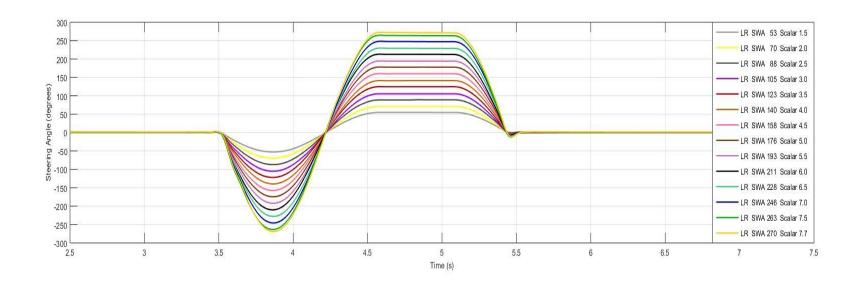


6.0 DATA PLOTS

| Figure 1. | Steering Angle and Yaw Rate Time History, Counter-Clockwise Initial Steer Tests |
|-----------|---|
| Figure 2. | Steering Angle, Lateral Acceleration, and Lateral Displacement Time History, Counter-Clockwise Initial Steer Tests |
| Figure 3. | Steering Angle and Yaw Rate Time History, Clockwise Initial Steer Tests |
| Figure 4. | Steering Angle, Lateral Acceleration, and Lateral Displacement Time History, Clockwise Initial Steer Tests |

6.0 2019 RAM 1500 DATA PLOTS

Figure 1. Steering Angle and Yaw Rate Time History, Counter-Clockwise Initial Steer Tests



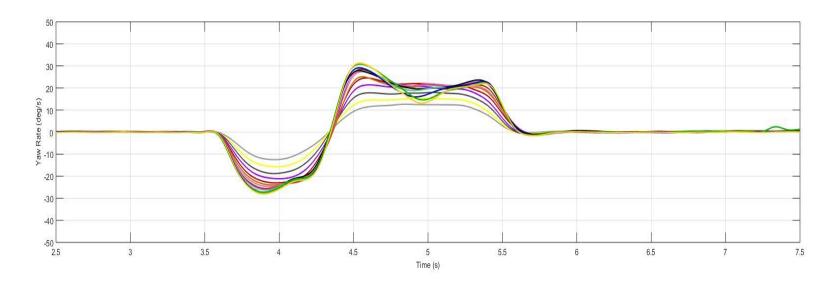
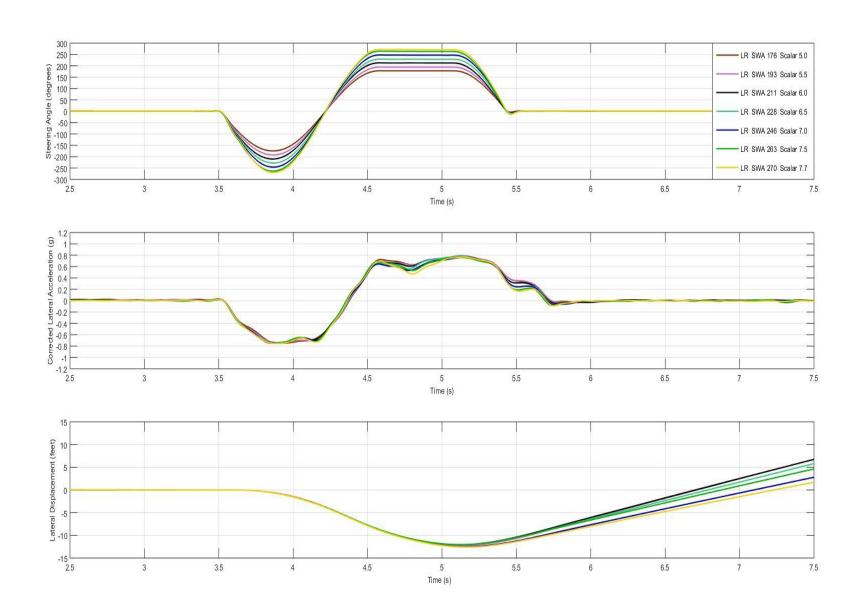
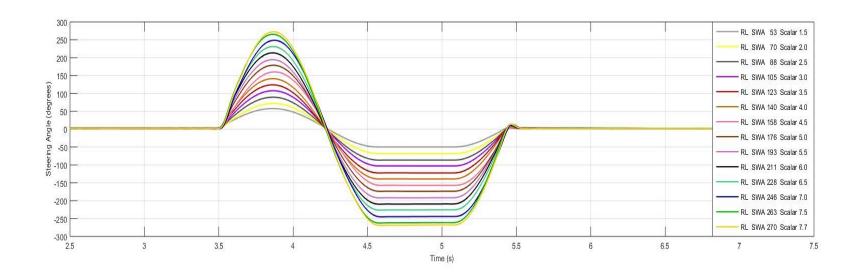


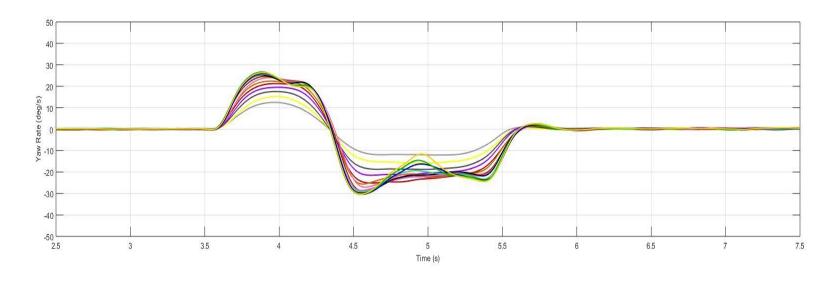
Figure 2. Steering Angle and Yaw Rate Time History, Counter-Clockwise Initial Steer Tests



2019 RAM 1500 DATA PLOTS ... continued

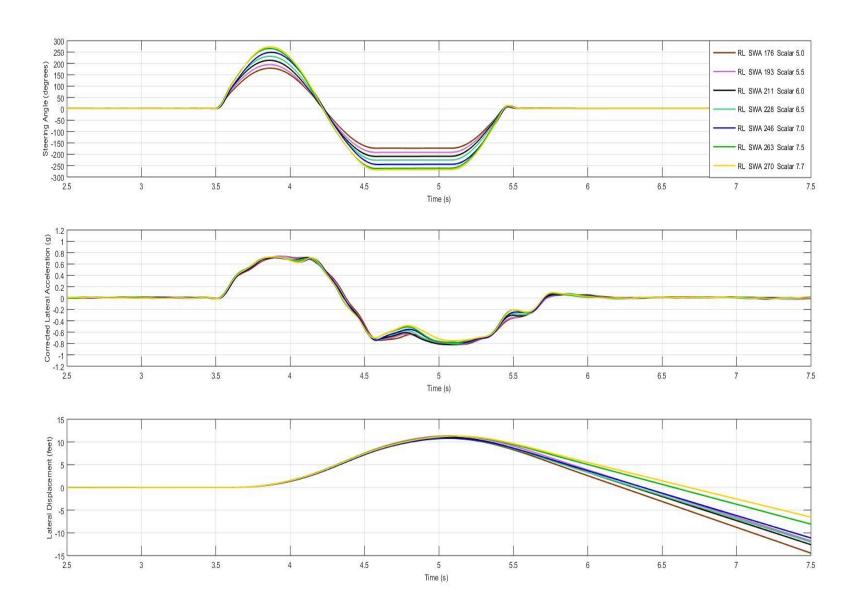
Figure 3. Steering Angle and Yaw Rate Time History, Clockwise Initial Steer Tests





9

Figure 4. Steering Angle, Lateral Acceleration, and Lateral Displacement Time History, Clockwise Initial Steer Tests



7.0 OTHER DOCUMENTATION

- 7.1 OWNER'S MANUAL PAGES
- 7.2 VEHICLE ARRIVAL CONDITION REPORT
- 7.3 VEHICLE COMPLETION CONDITION REPORT
- 7.4 SINE WITH DWELL TEST RESULTS
- 7.5 SLOWLY INCREASING STEER TEST RESULTS
- 7.6 INERTIA SENSOR MEASUREMENTS

- 6
- Turn the ignition to the OFF mode and then back to ON. If the sequence was completed properly, the "ESC Off Indicator Light" will blink several times to confirm HSA is disabled.
- 9. Repeat these steps if you want to return this feature to its previous setting.

Traction Control System (TCS)

This system monitors the amount of wheel spin of each of the driven wheels. If wheel spin is detected, the TCS may apply brake pressure to the spinning wheel(s) and/or reduce engine power to provide enhanced acceleration and stability. A feature of the TCS, Brake Limited Differential (BLD), functions similar to a limited slip differential and controls the wheel spin across a driven axle. If one wheel on a driven axle is spinning faster than the other, the system will apply the brake of the spinning wheel. This will allow more engine torque to be applied to the wheel that is not spinning. BLD may remain enabled even if TCS and ESC are in a reduced mode.

Electronic Stability Control (ESC)

This system enhances directional control and stability of the vehicle under various driving conditions. ESC corrects for oversteering or understeering of the vehicle by applying the brake of the appropriate wheel(s) to assist in counteracting the oversteer or understeer condition. Engine power may also be reduced to help the vehicle maintain the desired path.

ESC uses sensors in the vehicle to determine the vehicle path intended by the driver and compares it to the actual path of the vehicle. When the actual path does not match the intended path, ESC applies the brake of the appropriate wheel to assist in counteracting the oversteer or understeer condition.

- Oversteer when the vehicle is turning more than appropriate for the steering wheel position.
- Understeer when the vehicle is turning less than appropriate for the steering wheel position.

The "ESC Activation/Malfunction Indicator Light" located in the instrument cluster will start to flash as soon as the ESC system becomes active. The "ESC Activation/Malfunction Indicator Light" also flashes when the TCS is active. If the "ESC Activation/

Malfunction Indicator Light" begins to flash during acceleration, ease up on the accelerator and apply as little throttle as possible. Be sure to adapt your speed and driving to the prevailing road conditions.

WARNING!

Electronic Stability Control (ESC) cannot prevent the natural laws of physics from acting on the vehicle, nor can it increase the traction afforded by prevailing road conditions. ESC cannot prevent accidents, including those resulting from excessive speed in turns, driving on very slippery surfaces, or hydroplaning. ESC also cannot prevent accidents resulting from loss of vehicle control due to inappropriate driver input for the conditions. Only a safe, attentive, and skillful driver can prevent accidents. The capabilities of an ESC equipped vehicle must never be exploited in a reckless or dangerous manner which could jeopardize the user's safety or the safety of others.
 Vehicle modifications, or failure to properly

maintain your vehicle, may change the handling

(Continued)

WARNING! (Continued)

characteristics of your vehicle, and may negatively affect the performance of the ESC system. Changes to the steering system, suspension, braking system, tire type and size or wheel size may adversely affect ESC performance. Improperly inflated and unevenly worn tires may also degrade ESC performance. Any vehicle modification or poor vehicle maintenance that reduces the effectiveness of the ESC system can increase the risk of loss of vehicle control, vehicle rollover, personal injury and death.

ESC Operating Modes

NOTE: Depending upon model and mode of operation, the ESC system may have multiple operating modes.

ESC On

This is the normal operating mode for the ESC. Whenever the vehicle is started, the ESC system will be in this mode. This mode should be used for most driving conditions. Alternate ESC modes should only be used for specific reasons as noted in the following paragraphs.

0

Partial Off

The "Partial Off" mode is intended for times when a more spirited driving experience is desired. This mode may modify TCS and ESC thresholds for activation, which allows for more wheel spin than normally allowed. This mode may be useful if the vehicle becomes stuck.

To enter the "Partial Off" mode, momentarily push the "ESC Off" switch and the "ESC Off Indicator Light" will illuminate. To turn the ESC on again, momentarily push the "ESC Off" switch and the "ESC Off Indicator Light" will turn off.

NOTE: For vehicles with multiple partial ESC modes a momentary button push will toggle the ESC mode. Multiple momentary button pushed may be required to return to ESC On.

WARNING!

 When in "Partial Off" mode, the TCS functionality of ESC, (except for the limited slip feature described in the TCS section), has been disabled WARNING! (Continued)

and the "ESC Off Indicator Light" will be illuminated. When in "Partial Off" mode, the engine power reduction feature of TCS is disabled, and the enhanced vehicle stability offered by the ESC system is reduced.

• Trailer Sway control (TSC) is disabled when the ESC system is in the "Partial Off" mode.

Full Off — If Equipped

This mode is intended for off-highway or off-road use only and should not be used on any public roadways. In this mode, TCS and ESC features are turned OFF. To enter the "Full Off" mode, push and hold the "ESC Off" switch for five seconds while the vehicle is stopped with the engine running. After five seconds, a chime will sound, the "ESC Off Indicator Light" will illuminate, and the "ESC OFF" message will display in the instrument cluster. To turn ESC ON again, momentarily push the "ESC Off" switch.

(Continued)

NOTE: System may switch from ESC "Full Off" to "Partial Off" mode when vehicle exceeds a predetermined speed. When the vehicle speed slows below the predetermined speed the system will return to ESC "Full Off".

ESC modes may also be affected by drive modes if so equipped.

WARNING!

- In the ESC "Full Off" mode, the engine torque reduction and stability features are disabled. Therefore, enhanced vehicle stability offered by the ESC system is unavailable. In an emergency evasive maneuver, the ESC system will not engage to assist in maintaining stability. ESC "Full Off" mode is intended for off-highway or offroad use only.
- With the ESC switched off, the enhanced vehicle stability offered by ESC is unavailable. In an emergency evasive maneuver, the ESC system will not engage to assist in maintaining stability. ESC "Full Off" mode is only intended for offhighway or off-road use.

WARNING! (Continued)

 The Electronic Stability Control (ESC) cannot prevent the natural laws of physics from acting on the vehicle, nor can it increase the traction afforded by prevailing road conditions. ESC cannot prevent all accidents, including those resulting from excessive speed in turns, driving on very slippery surfaces, or hydroplaning. ESC also cannot prevent collisions.

ESC Activation/Malfunction Indicator Light and ESC OFF Indicator Light

art=GUID-040433445-low.png GrTrans=no



The "ESC Activation/Malfunction Indicator Light" in the instrument cluster will come on when the ignition is turned to the ON mode. It should go out with the engine running. If

the "ESC Activation/Malfunction Indicator Light" comes on continuously with the engine running, a malfunction has been detected in the ESC system. If this light remains on after several ignition cycles, and the vehicle has been driven several miles (kilometers) at

(Continued)

speeds greater than 30 mph (48 km/h), see your authorized dealer as soon as possible to have the problem diagnosed and corrected.

The "ESC Activation/Malfunction Indicator Light" (lo- art=GUID-054807480-low.png GrTrans=no cated in the instrument cluster) starts to flash as soon as the tires lose traction and the ESC system becomes active. The "ESC Activation/Malfunction Indicator Light" also flashes when TCS is active. If the "ESC Activation/Malfunction Indicator Light" begins to flash during acceleration, ease up on the accelerator and apply as little throttle as possible. Be sure to adapt your speed and driving to the prevailing road conditions.

NOTE:

- The "ESC Activation/Malfunction Indicator Light" and the "ESC OFF Indicator Light" come on momentarily each time the ignition is turned ON.
- Each time the ignition is turned ON, the ESC system will be on even if it was turned off previously.
- The ESC system will make buzzing or clicking

sounds when it is active. This is normal; the sounds will stop when ESC becomes inactive following the maneuver that caused the ESC activation.



The "ESC OFF Indicator Light" indicates the customer has elected to have the Electronic Stability Control (ESC) in a reduced mode.

Electronic Roll Mitigation (ERM)

This system anticipates the potential for wheel lift by monitoring the driver's steering wheel input and the speed of the vehicle. When ERM determines that the rate of change of the steering wheel angle and vehicle's speed are sufficient to potentially cause wheel lift, it then applies the appropriate brake and may also reduce engine power to lessen the chance that wheel lift will occur. ERM can only reduce the chance of wheel lift occurring during severe or evasive driving maneuvers; it cannot prevent wheel lift due to other factors, such as road conditions, leaving the roadway, or striking objects or other vehicles.

NOTE: ERM is disabled anytime the ESC is in "Full Off" mode (if equipped). Refer to "Electronic Stability Control (ESC)" in this section for a complete explanation of the available ESC modes.

WARNING!

Many factors, such as vehicle loading, road conditions and driving conditions, influence the chance that wheel lift or rollover may occur. ERM cannot prevent all wheel lift or roll overs, especially those that involve leaving the roadway or striking objects or other vehicles. The capabilities of an ERM-equipped vehicle must never be exploited in a reckless or dangerous manner which could jeopardize the user's safety or the safety of others.

Trailer Sway Control (TSC)

TSC uses sensors in the vehicle to recognize an excessively swaying trailer and will take the appropriate actions to attempt to stop the sway. TSC will become active automatically once an excessively swaying trailer is recognized.

NOTE: TSC cannot stop all trailers from swaying. Always use caution when towing a trailer and follow the trailer tongue weight recommendations. Refer to "Trailer Towing" in "Starting And Operating" for further information.

When TSC is functioning, the "ESC Activation/ Malfunction Indicator Light" will flash, the engine power may be reduced and you may feel the brakes being applied to individual wheels to attempt to stop the trailer from swaying. TSC is disabled when the ESC system is in the "Partial Off" or "Full Off" modes.

WARNING!

If TSC activates while driving, slow the vehicle down, stop at the nearest safe location, and adjust the trailer load to eliminate trailer sway.

Hill Descent Control (HDC) — If Equipped

HDC is intended for low speed off road driving while in 4WD Low Range. HDC maintains vehicle speed while descending hills during various driving situations. HDC controls vehicle speed by actively controlling the brakes.

HDC has three states:

7.2 VEHICLE ARRIVAL CONDITION REPORT

| CONTRACT NO. <u>DTNH22-16-D-00027</u> | DATE:7-8-19 |
|---|--|
| FROM: Automotive Allies | |
| TO: TRC Inc. | |
| TO: TRC Inc. PURPOSE: (X) Initial () Rece Receipt via Transfer | eived () Present r vehicle condition |
| MODEL YEAR/MAKE/MODEL/BODY STYLE: 20 | 019 / RAM / 1500 / Truck |
| MANUFACTURE DATE: 05-18 NHTS | SA NO.: <u>C20190303</u> |
| BODY COLOR: White V | IN: <u>1C6SRFGT1KN552167</u> |
| ODOMETER READING:35 miles | GVWR: <u>3,221</u> KG |
| PURCHASE PRICE: \$ rented / leased DEAL | |
| Findlay Chrysler Dodge Jeep Ram, 10305 | St Rt. 224W, Findlay, OH |
| X ALL OPTIONS LISTED ON "WINDOW STICKI VEHICLE X TIRES AND WHEEL RIMS ARE NEW AND THE | |
| X THERE ARE NO DENTS OR OTHER INTERIOR | |
| | |
| X THE VEHICLE HAS BEEN PROPERLY PREP CONDITION | PARED AND IS IN RUNNING |
| X THE GLOVE BOX CONTAINS AN OWNER'S CONSUMER INFORMATION, AND EXTRA SI | |
| X PROPER FUEL FILLER CAP IS SUPPLIED O | ON THE TEST VEHICLE |
| X PLACE VEHICLE IN STORAGE AREA | |
| X INSPECT THE VEHICLE'S INTERIOR AND E SEATS, DOORS, ETC., TO CONFIRM THA FUNCTIONAL PER THE MANUFACTURER MISADJUSTMENT, OR OTHER UNUSUAL THE TEST PROGRAM OR TEST RESULTS ABNORMAL CONDITION TO THE NHTSA CO | AT EACH SYSTEM IS COMPLETE AND R'S SPECIFICATIONS. ANY DAMAGE CONDITION THAT COULD INFLUENCE SHALL BE RECORDED. REPORT ANY |
| RECORDED BY: <u>David Karls</u> APPROVED BY: Jordan Piening | DATE: 7-30-19 DATE: 7-30-19 |

7.3 VEHICLE COMPLETION CONDITION REPORT

| CONTRACT NO. <u>DTNH22-16-D-000</u> | 27 DATE: 7-26-19 |
|--|---|
| MODEL YEAR/MAKE/MODEL/BODY S | TYLE: 2019 / RAM / 1500 / Truck |
| MANUFACTURE DATE: 05-18 | NHTSA NO.:C20190303 |
| BODY COLOR: White | VIN: 1C6SRFGT1KN552167 |
| ODOMETER READING: <u>84</u> miles | GVWR: <u>3,221</u> KG |
| LIST OF FMVSS TESTS PERFORMED | BY THIS LAB: <u>126, 135</u> |
| | R INTERIOR OR EXTERIOR FLAWS |
| CONDITION X THE GLOVE BOX CONTAINS AN CONSUMER INFORMATION, AND | DWNER'S MANUAL, WARRANTY DOCUMENT, EXTRA SET OF KEYS |
| X PROPER FUEL FILLER CAP IS SU | PPLIED ON THE TEST VEHICLE |
| REMARKS: | |
| Equipment that is no longer on the test report: None. | vehicle as noted on Vehicle Arrival Condition |
| Explanation for equipment removal: N/A | |
| Test Vehicle Condition: Like new. | |
| RECORDED BY: David Karls APPROVED BY: Jordan Piening | DATE: 7-30-19 DATE: 7-30-19 |

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| 7.4 SINE W | ITH DWELL T | EST RESI | JLTS | | | | | | | | | |
|----------------------|-------------------|------------------|----------------|--------------|----------------|------------|----------------|------------------|----------------|--------------|------------------|----------------|
| 2019 RAM | | | | | | | | | | | | |
| | .: C20190303 | | | | | | | | | | | |
| | | | | | | | | | | | | |
| Date Created | 24-Jul-19 | | | | | | | | | | | |
| | | | | | | | | | | | | |
| | | | | | | | | | | | | |
| LEFT-TO-RIGI | HT (INITIAL COUN | TER-CLOCK | (WISE STEER) | | | | | | | | | |
| | | | | | | | | | | | | |
| File | SWA @ 5deg Ct | MES | Time@5deg | cos | Time@COS | MOS | Time@MOS | YRR1(%) | YR1 (deg/sec) | YRR1 Ct | YRR175(%) | YR175 (deg/sed |
| 0014 | 708 | 49.514 | 3.533 | 1090 | 5.443 | 846 | 4.224 | 0.710 | 0.089 | 1290 | 4.244 | 0.532 |
| 0015 | 707 | 49.658 | 3.526 | 1090 | 5.441 | 846 | 4.222 | -0.661 | -0.096 | 1290 | 1.262 | 0.183 |
| 0016 | 706 | 49.731 | 3.523 | 1089 | 5.440 | 846 | 4.223 | -0.788 | -0.140 | 1289 | 2.678 | 0.477 |
| 0017 | 705 | 49.787 | 3.519 | 1089 | 5.439 | 845 | 4.220 | -0.757 | -0.162 | 1289 | 2.329 | 0.499 |
| 0018 | 705 | 49.589 | 3.516 | 1089 | 5.437 | 845 | 4.218 | -0.842 | -0.206 | 1289 | 1.704 | 0.417 |
| 0019 | 705 | 49.922 | 3.518 | 1089 | 5.440 | 846 | 4.221 | -0.052 | -0.013 | 1289 | 0.752 | 0.188 |
| 0020 | 705 | 49.678 | 3.516 | 1089 | 5.437 | 845 | 4.219 | -0.648 | -0.176 | 1289 | 1.143 | 0.310 |
| 0021 | 705 | 49.638 | 3.517 | 1089 | 5.437 | 846 | 4.220 | -0.495 | -0.140 | 1289 | 0.757 | 0.213 |
| 0022 | 705 | 49.642 | 3.518 | 1089 | 5.438 | 846 | 4.221 | -0.519 | -0.142 | 1289 | 0.425 | 0.116 |
| 0023 | 704 | 49.849 | 3.515 | 1088 | 5.433 | 845 | 4.218 | 0.091 | 0.025 | 1288 | 0.296 | 0.082 |
| 0024 | 705 | 49.423 | 3.520 | 1089 | 5.437 | 846 | 4.222 | 0.091 | 0.026 | 1289 | 0.892 | 0.260 |
| 0025 | 706 | 49.946 | 3.521 | 1089 | 5.437 | 846 | 4.221 | -0.512 | -0.149 | 1289 | 0.325 | 0.094 |
| 0026 | 705 | 49.588 | 3.516 | 1088 | 5.432 | 845 | 4.217 | 0.325 | 0.100 | 1288 | 0.925 | 0.286 |
| 0027 | 706 | 49.477 | 3.520 | 1089 | 5.436 | 846 | 4.221 | -0.222 | -0.069 | 1289 | -0.249 | -0.078 |
| | | | | | | | | | | | | |
| RIGHT-TO-LE | FT (INITIAL CLOC | KWISE STE | ER) | | | | | | | | | |
| | | | | | | | | | | | | |
| File | SWA @ 5deg Ct | MES | Time@5deg | cos | Time@COS | MOS | Time@MOS | YRR1(%) | YR1 (deg/sec) | YRR1 Ct | YRR175(%) | YR175 (deg/sec |
| 0028 | 708 | 49.461 | 3.531 | 1090 | 5.441 | 845 | 4.218 | 1.030 | -0.126 | 1290 | -0.095 | 0.012 |
| 0029 | 707 | 49.907 | 3.529 | 1090 | 5.444 | 846 | 4.222 | -0.531 | 0.084 | 1290 | -2.543 | 0.401 |
| 0030 | 706 | 49.330 | 3.523 | 1090 | 5.441 | 845 | 4.219 | 0.634 | -0.118 | 1290 | -4.184 | 0.778 |
| 0031 | 706 | 49.634 | 3.522 | 1090 | 5.440 | 845 | 4.220 | -0.976 | 0.209 | 1290 | -2.176 | 0.467 |
| 0032 | 705 | 49.697 | 3.516 | 1089 | 5.437 | 845 | 4.217 | -1.175 | 0.292 | 1289 | -2.652 | 0.659 |
| 0033 | 705 | 49.657 | 3.517 | 1089 | 5.438 | 845 | 4.218 | -1.476 | 0.374 | 1289 | -0.431 | 0.109 |
| 0034 | 707 | 49.608 | 3.529 | 1091 | 5.450 | 848 | 4.230 | -1.171 | 0.317 | 1291 | -1.770 | 0.479 |
| 0035 | 705 | 49.762 | 3.520 | 1089 | 5.440 | 846 | 4.221 | -1.184 | 0.343 | 1289 | 0.248 | -0.072 |
| 0036 | 705 | 49.789 | 3.516 | 1088 | 5.435 | 845 | 4.217 | -0.882 | 0.252 | 1288 | -0.498 | 0.142 |
| 0037 | 704 | 49.721 | 3.515 | 1088 | 5.433 | 845 | 4.216 | -0.844 | 0.251 | 1288 | 0.400 | -0.119 |
| | | 49.429 | 3.518 | 1089 | 5.436 | 845 | 4.219 | -0.264 | 0.078 | 1289 | 0.218 | -0.064 |
| 0038 | /05 | | | | | | | | | | | |
| 0038 0039 | 705 707 | | | 1090 | 5.444 | 847 | 4.228 | -1.343 | 0.407 | 1290 | -0.739 | 0.224 |
| 0038 0039 0040 | 705 707 705 | 49.615 49.788 | 3.527 3.516 | 1090 1088 | 5.444 5.433 | 847 845 | 4.228 4.217 | -1.343 -0.001 | 0.407 0.000 | 1290 1288 | -0.739 -0.511 | 0.224 0.155 |

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| 7.4 SINE V | VITH DWE | LL TEST RESULTS | | | | | | |
|--------------|-------------|-----------------------|-----------------|----------------|---------------------|-------------------|-----------------|------------------|
| 2019 RAM | 1500 | | | | | | | |
| NHTSA No | | 0303 | | | | | | |
| | | | | | | | | |
| Date Created | 24-Jul-19 | | | | | | | |
| | | | | | | | | |
| I FFT-TO-RIG | HT (INITIAL | COUNTER-CLOCKWISE | STEER) | | | | | |
| | | | , | | | | | |
| File | YRR175 Ct | 2nd Yaw Peak(deg/sec) | 2nd Yaw Peak Ct | Lat Disp (ft) | Lat. Acc. 1.07s (g) | 1st SWA Peak(deg) | 1st SWA Peak Ct | 2nd SWA Mean(deg |
| 0014 | 1440 | 12.542 | 971 | -4.289 | 0.411 | 53.876 | 774 | 53.759 |
| 0015 | 1440 | 14.525 | 928 | -5.375 | 0.500 | 70.276 | 774 | 70.187 |
| 0016 | 1439 | 17.802 | 923 | -6.493 | 0.557 | 88.120 | 774 | 87.899 |
| 0017 | 1439 | 21.411 | 922 | -7.312 | 0.620 | 105.302 | 774 | 105.309 |
| 0018 | 1439 | 24.459 | 918 | -7.959 | 0.656 | 123.340 | 773 | 123.369 |
| 0019 | 1439 | 24.983 | 913 | -8.415 | 0.661 | 140.462 | 774 | 140.291 |
| 0020 | 1439 | 27.151 | 912 | -8.663 | 0.700 | 158.847 | 774 | 158.745 |
| 0021 | 1439 | 28.190 | 911 | -8.873 | 0.711 | 176.445 | 774 | 176.199 |
| 0022 | 1439 | 27.402 | 910 | -8.936 | 0.684 | 193.504 | 774 | 193.161 |
| 0023 | 1438 | 27.770 | 908 | -8.865 | 0.671 | 211.797 | 773 | 211.211 |
| 0024 | 1439 | 29.104 | 909 | -8.831 | 0.663 | 228.871 | 774 | 228.277 |
| 0025 | 1439 | 29.010 | 909 | -8.983 | 0.635 | 246.898 | 774 | 246.230 |
| 0026 | 1438 | 30.898 | 910 | -8.865 | 0.682 | 264.007 | 774 | 263.132 |
| 0027 | 1439 | 31.272 | 909 | -9.021 | 0.690 | 270.742 | 774 | 269.920 |
| | | | | | | | | |
| RIGHT-TO-LE | FT (INITIAL | CLOCKWISE STEER) | | | | | | |
| File | VDD17E C+ | 2nd Yaw Peak(deg/sec) | 2nd Yaw Book Ct | Lat Dica (ft) | Lat Acc 1.07c (g) | 1st SWA Book/dog) | 1ct SWA Book Ct | 2nd SWA Mean(deg |
| 0028 | 1440 | -12.199 | 938 | 4.149 | -0.417 | 53.662 | 774 | 53.645 |
| 0028 | 1440 | -15.768 | 987 | 5.091 | -0.503 | 69.967 | 774 | 70.193 |
| 0023 | 1440 | -18.589 | 933 | 5.981 | -0.584 | 87.779 | 774 | 88.139 |
| 0031 | 1440 | -21.449 | 925 | 6.807 | -0.632 | 105.159 | 774 | 105.125 |
| 0031 | 1439 | -24.848 | 925 | 7.413 | -0.675 | 123.042 | 773 | 123.366 |
| 0032 | 1439 | -25.354 | 914 | 7.415 | -0.691 | 140.097 | 774 | 140.409 |
| 0034 | 1441 | -27.083 | 916 | 8.271 | -0.721 | 158.657 | 776 | 158.762 |
| 0034 | 1439 | -28.969 | 913 | 8.317 | -0.753 | 176.169 | 774 | 176.340 |
| 0036 | 1439 | -28.533 | 912 | 8.582 | -0.728 | 193.215 | 774 | 193.170 |
| 0030 | 1438 | -29.763 | 910 | 8.446 | -0.735 | 211.580 | 773 | 211.245 |
| 0037 | 1438 | -29.448 | 911 | 8.446 8.363 | -0.733 | 228.662 | 774 | 228.314 |
| 0038 | | | 913 | | | | 774 | |
| | 1440 | -30.278 | | 8.316 | -0.740 | 246.666 | | 246.327 |
| 0040 | 1438 | -30.413 | 911 | 8.505 | -0.695 | 263.645 | 774 | 263.338 |
| 0041 | 1439 | -30.335 | 910 | 8.453 | -0.691 | 270.554 | 774 | 270.065 |

| 2019 RAM 15 | 500 | | | | | | | | | | |
|--------------|---------------|-------------|----------|-----------|----------------|-----------|----------------------|----------------|-----------|-----------|---------|
| NHTSA No.: | | | | | | | | | | | |
| | | | | | | | | | | | |
| Date Created | | 24-Jul-19 | | | | | | | | | |
| | | | | | _ | | | | | | |
| | | | | | | | | | | | |
| File | Vehicle | EventPt | DOS | MES [mph] | Mean SPD [mph] | AYcount_3 | THETAENCF_3 [degree] | AYCG_CD2_3 [g] | r_squared | ZeroBegin | ZeroEnd |
| 0006 | 2019 RAM 1500 | 696 | 1 | 50.400 | 50.458 | 1216 | -35.172 | -0.302 | 0.998 | 496 | 696 |
| 0008 | 2019 RAM 1500 | 680 | 1 | 49.940 | 49.878 | 1223 | -35.411 | -0.307 | 0.996 | 480 | 680 |
| 0009 | 2019 RAM 1500 | 694 | 1 | 49.354 | 49.358 | 1221 | -35.556 | -0.309 | 0.996 | 494 | 694 |
| 0010 | 2019 RAM 1500 | 705 | 0 | 50.562 | 50.448 | 1207 | 34.084 | 0.303 | 0.994 | 505 | 705 |
| 0011 | 2019 RAM 1500 | 705 | 0 | 49.773 | 49.806 | 1225 | 35.237 | 0.305 | 0.996 | 505 | 705 |
| 0012 | 2019 RAM 1500 | 707 | 0 | 50.594 | 50.138 | 1223 | 35.008 | 0.298 | 0.996 | 507 | 707 |
| | Averages | | | | | | 35.1 | 0.304 | | | |
| | | | | | | | | | | | |
| | Scalars | Steering An | gles (de | eg) | | | | | | | |
| | 1.5 | 53 | | | | | | | | | |
| | 2.0 | 70 | | | | | | | | | |
| | 2.5 | 88 | | | | | | | | | |
| | 3.0 | 105 | | | | | | | | | |
| | 3.5 | 123 | | | | | | | | | |
| | 4.0 | 140 | | | | | | | | | |
| _ | 4.5 | 158 | | | | | | | | | |
| | 5.0 | 176 | | | | | | | | | |
| | 5.5 | 193 | | | | | | | | | |
| | 6.0 | 211 | | | | | | | | | |
| | 6.5 | 228 | | | | | | | | | |
| | 7.0 | 246 | | | | | | | | | |
| | 7.5 | 263 | | | | | | | | | |
| | 7.7 | 270 | | | | | | | | | |

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| 7.6 INERTIA SENSOR | MEASUREME | NTS | | | | | | |
|---------------------------|-------------|----------|----------|----------------------------------|--|---------|----------|--|
| 2019 RAM 1500 | | | | | | | | |
| NHTSA No.: C201903 | 303 | | | | | | | |
| Device : U12- | 05-08-07108 | | | x-distance (longitudinal) | Point of reference is the front axle centerline. | | | |
| device version : 2.2 | 25 | | | | (Positive from front axle toward rear of vehicle.) | | | |
| device certification date | : 9/19/18 | | | | | | | |
| today is : 7/23/19 | 9 | | | y-distance (lateral) | Point of reference is the vehicle centerline. | | | |
| units : Millir | meters | | | | (Positive from the center toward the right.) | | | |
| Label | ActualX | ActualY | ActualZ | z-distance (vertical) | Point of reference is the ground plane. | | | |
| | | | | , | (Positive from the ground up.) | | | |
| | | | | Roof Height (relative to ground) | | | 1905.449 | |
| M_FRT_AXLE_CENTER | 0 | 0 | 0 | Motion Pak - x-distance (mm) | 1905.946 | | | |
| C_COORDSYS001 | 0 | 0 | 0 | Motion Pak - y-distance (mm) | | -27.732 | | |
| M_TIRE_TREAD_CENTER | 341.1622 | 76.60533 | -228.381 | Motion Pak - z-distance (mm) | | | 1079.272 | |
| M_INERTIA_PACK | 1905.946 | 916.3732 | 795.4297 | | | | | |
| M_ROOF | 2337.116 | 935.3223 | 1532.706 | | | | | |
| M_GROUND | 2336.199 | -305.718 | -372.743 | Motion Pak - x-distance (inches) | 75.037 | | | |
| M_REAR_AXLE_CENTER | 3673.553 | 2.250638 | 4.9538 | Motion Pak - y-distance (inches) | | -1.092 | | |
| Track Width | | 1735 | | Motion Pak - z-distance (inches) | | | 42.491 | |